

Failure of full abstraction

$\exists M_1, M_2 \in \text{PCF}_c$

s.t. $M_1 \underset{\text{def}}{\equiv} M_2$

but

$$\llbracket M_1 \rrbracket \neq \llbracket M_2 \rrbracket$$

We will work at higher types τ ,

$$\text{say } \tau = \tau_1 \rightarrow \tau_2$$

$$M_1 \underset{\text{def}}{\equiv} M_2 : \tau_1 \rightarrow \tau_2$$

iff

$$\forall N. M_1 N \Downarrow v \text{ iff } M_2 N \Downarrow v$$

$$(M_1)(\llbracket N \rrbracket) = \llbracket M_1 N \rrbracket = \llbracket v \rrbracket \quad \llbracket v \rrbracket = \llbracket M_2 N \rrbracket = (M_2)(\llbracket N \rrbracket)$$

$$\llbracket M_1 \rrbracket \neq \llbracket M_2 \rrbracket : \llbracket \tau_1 \rrbracket \rightarrow \llbracket \tau_2 \rrbracket$$

iff

$$\exists d \in \llbracket \tau_1 \rrbracket. \llbracket M_1 \rrbracket d \neq \llbracket M_2 \rrbracket d$$

We look for non-definable d 's!

$\forall z. \perp \in \Gamma[z:y]$

is definable by

$$\Omega = \text{fix}(\text{fn } z : \tau . z)$$

$\Omega \Downarrow$

Suppose $\Omega \Downarrow V$

Then there is a smallest derivation of this fact.

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Ω
" "

and the
analysis

$z[\Omega/x] \Downarrow V$

$\text{fn } z . z \Downarrow \text{fn } z . z$

$$\frac{\text{fn } z . z \Downarrow \text{fn } z . z}{(\text{fn } z . z)(\Omega) \Downarrow V}$$

leads to
contradiction.

A non-definable function

$$\underline{\text{por}} \in B_\perp \rightarrow B_\perp \rightarrow B_\perp$$

$$\left\{ \begin{array}{l} \underline{\text{por}}(\underline{\text{true}}) \perp = \underline{\text{true}} \\ \underline{\text{por}}(\perp) \underline{\text{true}} = \underline{\text{true}} \\ \underline{\text{por}} \underline{\text{false}} \underline{\text{false}} = \underline{\text{false}} \end{array} \right.$$

There is no

$$M \in \text{PCF}_{\text{bool} \rightarrow \text{bool} \rightarrow \text{bool}}$$

s.t.

$$\bar{x} M \bar{y} = \underline{\text{por}}$$

→ operationally .

→ stable model .

$$\llbracket T_1 \rrbracket : (B_\perp \rightarrow B_\perp \rightarrow B_\perp) \rightarrow B_\perp$$

$$\llbracket T_1 \rrbracket (f) = \begin{cases} \text{true} & \text{if } f = \underline{\text{por}} \\ \perp & \text{otherwise.} \end{cases}$$

$$\llbracket T_2 \rrbracket (f) = \begin{cases} \text{false} & \text{if } f = \underline{\text{xor}} \\ \perp & \text{otherwise} \end{cases}$$

$\forall M : \text{bool} \rightarrow \text{bool} \rightarrow \text{bool}$

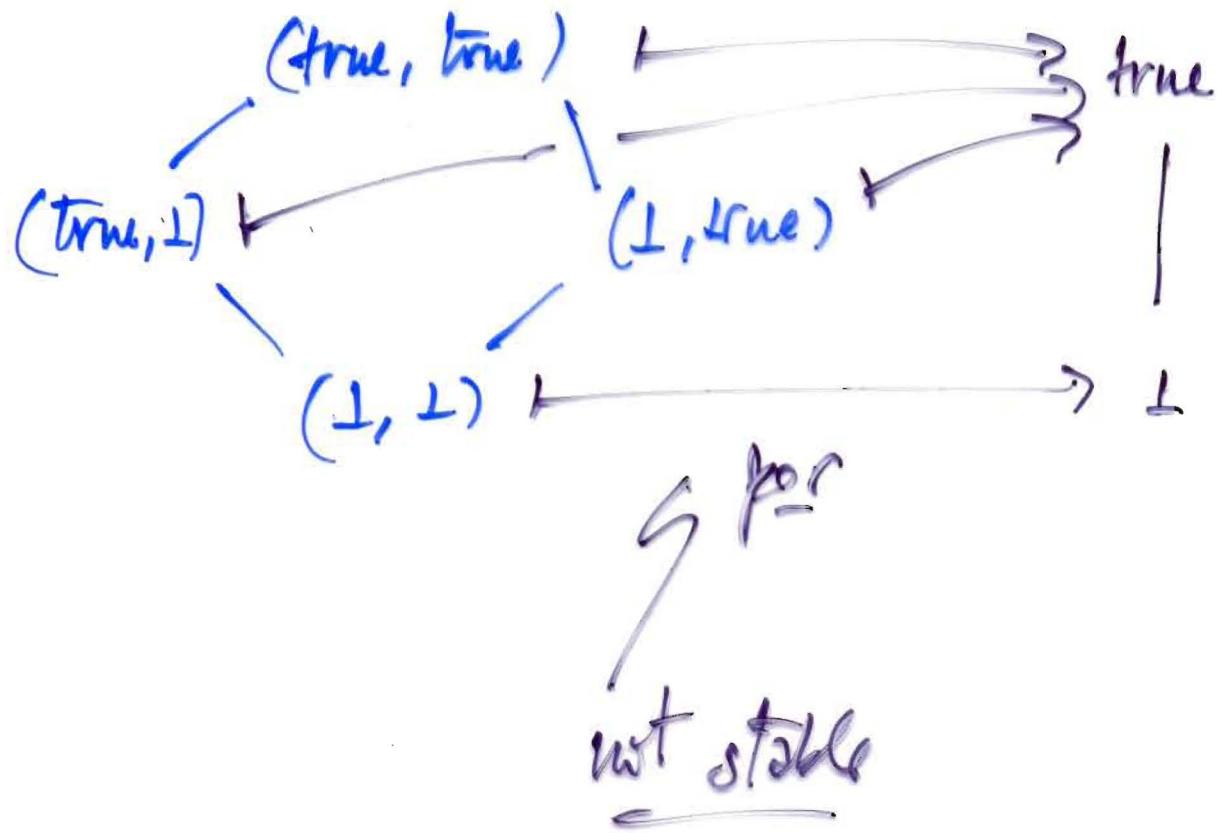
$$T_1(M) \not\vdash \quad \& \quad T_2(M) \not\vdash$$

and so

$$T_1 \leq_{\text{dfr}} T_2$$

Stability

$$\mathbb{B}_\perp \times \mathbb{B}_\perp$$



por : bool \rightarrow bool \rightarrow bool

{ por : bool \times bool \rightarrow bool