

L11: Algebraic Path Problems with applications to Internet Routing

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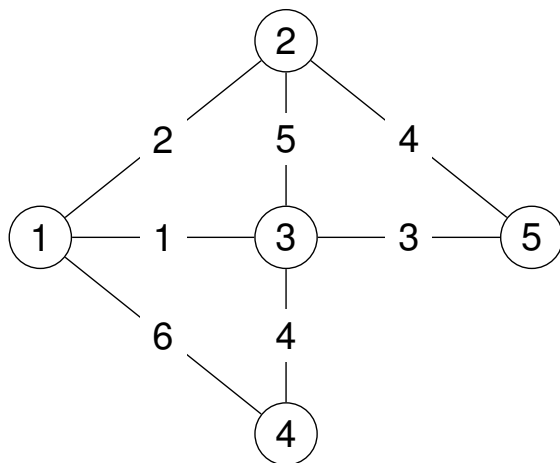
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Shortest paths example, $sp = (\mathbb{N}^\infty, \min, +, \infty, 0)$



The adjacency matrix

$$\mathbf{A} = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \begin{bmatrix} \infty & 2 & 1 & 6 & \infty \\ 2 & \infty & 5 & \infty & 4 \\ 1 & 5 & \infty & 4 & 3 \\ 6 & \infty & 4 & \infty & \infty \\ \infty & 4 & 3 & \infty & \infty \end{bmatrix} \end{matrix}$$

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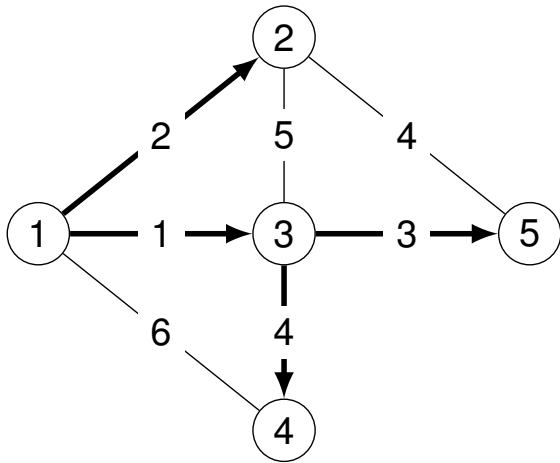
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Shortest paths solution



$$\mathbf{A}^* = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \begin{bmatrix} 0 & 2 & 1 & 5 & 4 \\ 2 & 0 & 3 & 7 & 4 \\ 1 & 3 & 0 & 4 & 3 \\ 5 & 7 & 4 & 0 & 7 \\ 4 & 4 & 3 & 7 & 0 \end{bmatrix} \end{matrix}$$

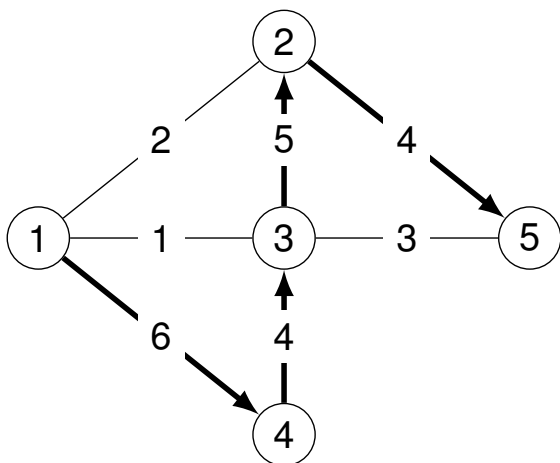
solves this **global optimality** problem:

$$\mathbf{A}^*(i, j) = \min_{p \in \pi(i, j)} w(p),$$

where $\pi(i, j)$ is the set of all paths from i to j .

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Widest paths example, $\text{bw} = (\mathbb{N}^\infty, \max, \min, 0, \infty)$



$$\mathbf{A}^* = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \begin{bmatrix} \infty & 4 & 4 & 6 & 4 \\ 4 & \infty & 5 & 4 & 4 \\ 4 & 5 & \infty & 4 & 4 \\ 6 & 4 & 4 & \infty & 4 \\ 4 & 4 & 4 & 4 & \infty \end{bmatrix} \end{matrix}$$

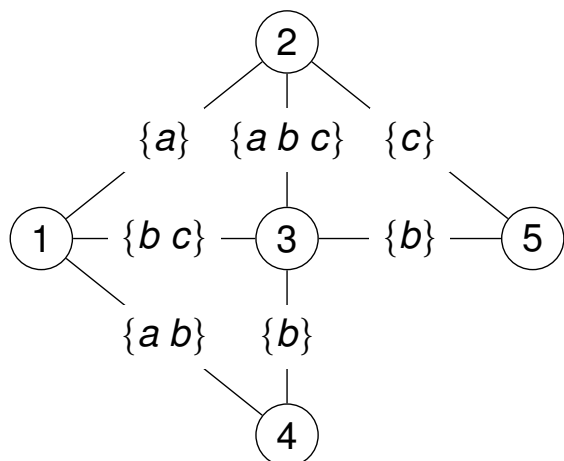
solves this global optimality problem:

$$\mathbf{A}^*(i, j) = \max_{p \in \pi(i, j)} w(p),$$

where $w(p)$ is now the minimal edge weight in p .

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Unfamiliar example, $(2^{\{a, b, c\}}, \cup, \cap, \{\}, \{a, b, c\})$



We want \mathbf{A}^* to solve this global optimality problem:

$$\mathbf{A}^*(i, j) = \bigcup_{p \in \pi(i, j)} w(p),$$

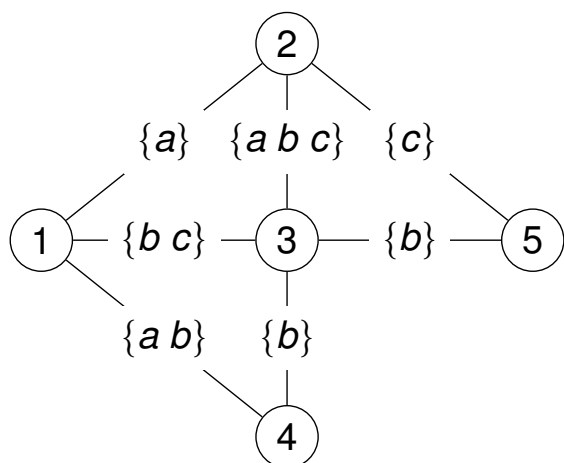
where $w(p)$ is now the intersection of all edge weights in p .

For $x \in \{a, b, c\}$, interpret $x \in \mathbf{A}^*(i, j)$ to mean that there is at least one path from i to j with x in every arc weight along the path.

$$\mathbf{A}^*(4, 1) = \{a, b\} \quad \mathbf{A}^*(4, 5) = \{b\}$$

Navigation icons: back, forward, search, etc.

Another unfamiliar example, $(2^{\{a, b, c\}}, \cap, \cup)$



We want matrix \mathbf{R} to solve this global optimality problem:

$$\mathbf{A}^*(i, j) = \bigcap_{p \in \pi(i, j)} w(p),$$

where $w(p)$ is now the union of all edge weights in p .

For $x \in \{a, b, c\}$, interpret $x \in \mathbf{A}^*(i, j)$ to mean that every path from i to j has at least one arc with weight containing x .

$$\mathbf{A}^*(4, 1) = \{b\} \quad \mathbf{A}^*(4, 5) = \{b\} \quad \mathbf{A}^*(5, 1) = \{\}$$

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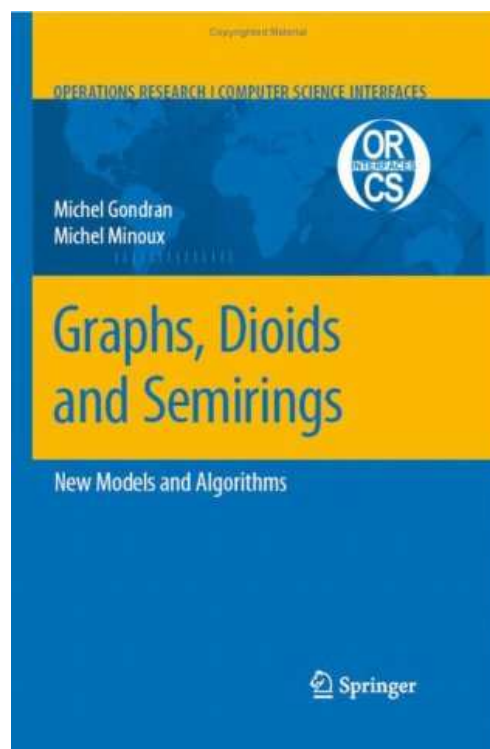
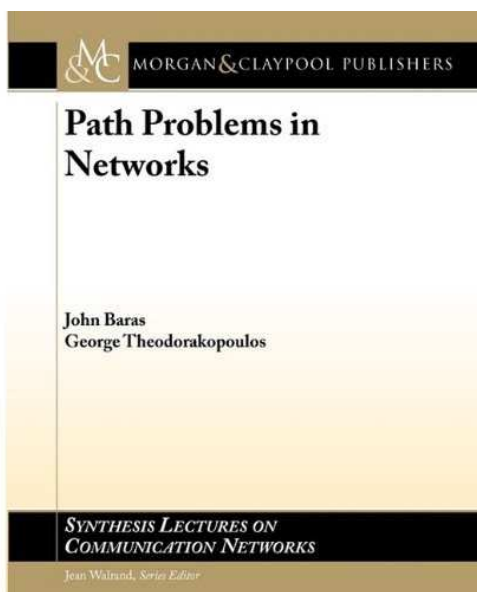
Semirings (generalise $(\mathbb{R}, +, \times, 0, 1)$)

name	S	\oplus ,	\otimes	$\bar{0}$	$\bar{1}$	possible routing use
sp	\mathbb{N}^∞	min	+	∞	0	minimum-weight routing
bw	\mathbb{N}^∞	max	min	0	∞	greatest-capacity routing
rel	$[0, 1]$	max	\times	0	1	most-reliable routing
use	$\{0, 1\}$	max	min	0	1	usable-path routing
	2^W	\cup	\cap	$\{\}$	W	shared link attributes?
	2^W	\cap	\cup	W	$\{\}$	shared path attributes?

A wee bit of notation!

Symbol	Interpretation
\mathbb{N}	Natural numbers (starting with zero)
\mathbb{N}^∞	Natural numbers, plus infinity
$\bar{0}$	Identity for \oplus
$\bar{1}$	Identity for \otimes

Recommended (on reserve in CL library)



Semiring axioms ...

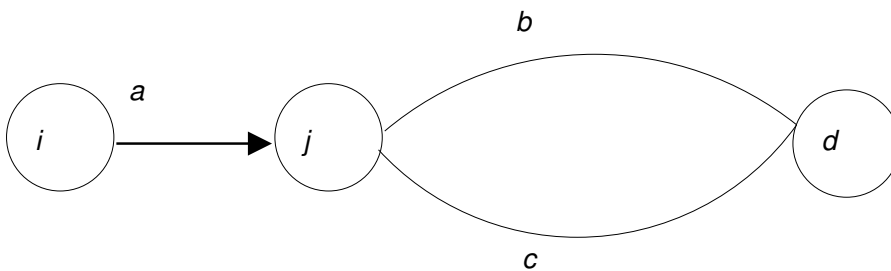
We will look at all of the axioms of semirings, but the most important are

distributivity

$$\text{LD} : a \otimes (b \oplus c) = (a \otimes b) \oplus (a \otimes c)$$

$$\text{RD} : (a \oplus b) \otimes c = (a \otimes c) \oplus (b \otimes c)$$

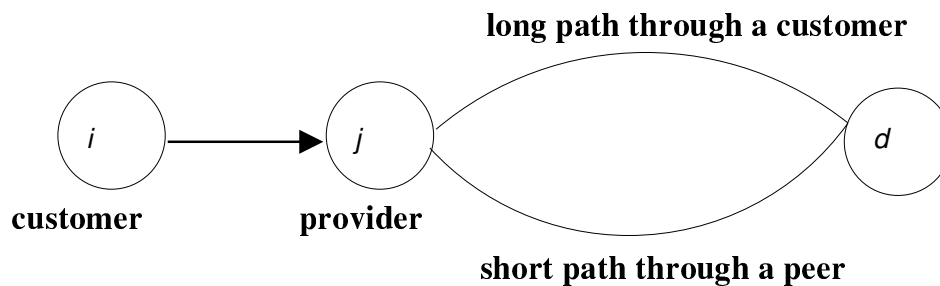
Distributivity, illustrated



$$a \otimes (b \oplus c) = (a \otimes b) \oplus (a \otimes c)$$

$$j \text{ makes the choice} = i \text{ makes the choice}$$

Should distributivity hold in Internet Routing?

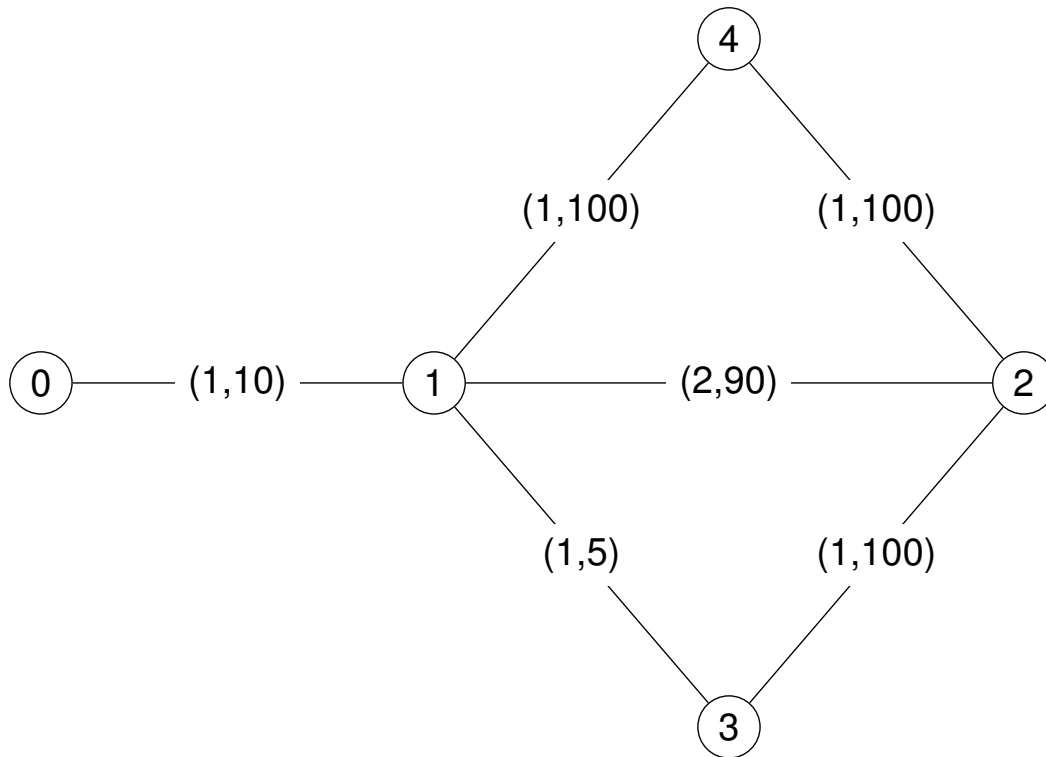


- *j* prefers long path through one of its customers (not the shorter path through a competitor)
- given two routes from a provider, *i* prefers the one with a shorter path
- More on inter-domain routing in the Internet later in the term ...

Widest shortest-paths

- Metric of the form (d, b) , where d is distance (min, +) and b is capacity (max, min).
- Metrics are compared lexicographically, with distance considered first.
- Such things are found in the vast literature on Quality-of-Service (QoS) metrics for Internet routing.

Widest shortest-paths



Navigation icons: back, forward, search, etc.

Weights are globally optimal (we have a semiring)

Widest shortest-path weights computed by Dijkstra and Bellman-Ford

$$\mathbf{R} = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \left[\begin{array}{ccccc} (0, \infty) & (1, 10) & (3, 10) & (2, 5) & (2, 10) \\ (1, 10) & (0, \infty) & (2, 100) & (1, 5) & (1, 100) \\ (3, 10) & (2, 100) & (0, \infty) & (1, 100) & (1, 100) \\ (2, 5) & (1, 5) & (1, 100) & (0, \infty) & (2, 100) \\ (2, 10) & (1, 100) & (1, 100) & (2, 100) & (0, \infty) \end{array} \right] \end{matrix}$$

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But what about the paths themselves?

Four optimal paths of weight (3, 10).

$$\begin{aligned}\mathbf{P}_{\text{optimal}}(0, 2) &= \{(0, 1, 2), (0, 1, 4, 2)\} \\ \mathbf{P}_{\text{optimal}}(2, 0) &= \{(2, 1, 0), (2, 4, 1, 0)\}\end{aligned}$$

There are standard ways to extend Bellman-Ford and Dijkstra to compute paths (or the associated next hops).

Do these extended algorithms find all optimal paths?

Surprise!

Four **optimal** paths of weight (3, 10)

$$\begin{aligned}\mathbf{P}_{\text{optimal}}(0, 2) &= \{(0, 1, 2), (0, 1, 4, 2)\} \\ \mathbf{P}_{\text{optimal}}(2, 0) &= \{(2, 1, 0), (2, 4, 1, 0)\}\end{aligned}$$

Paths computed by (extended) **Dijkstra**

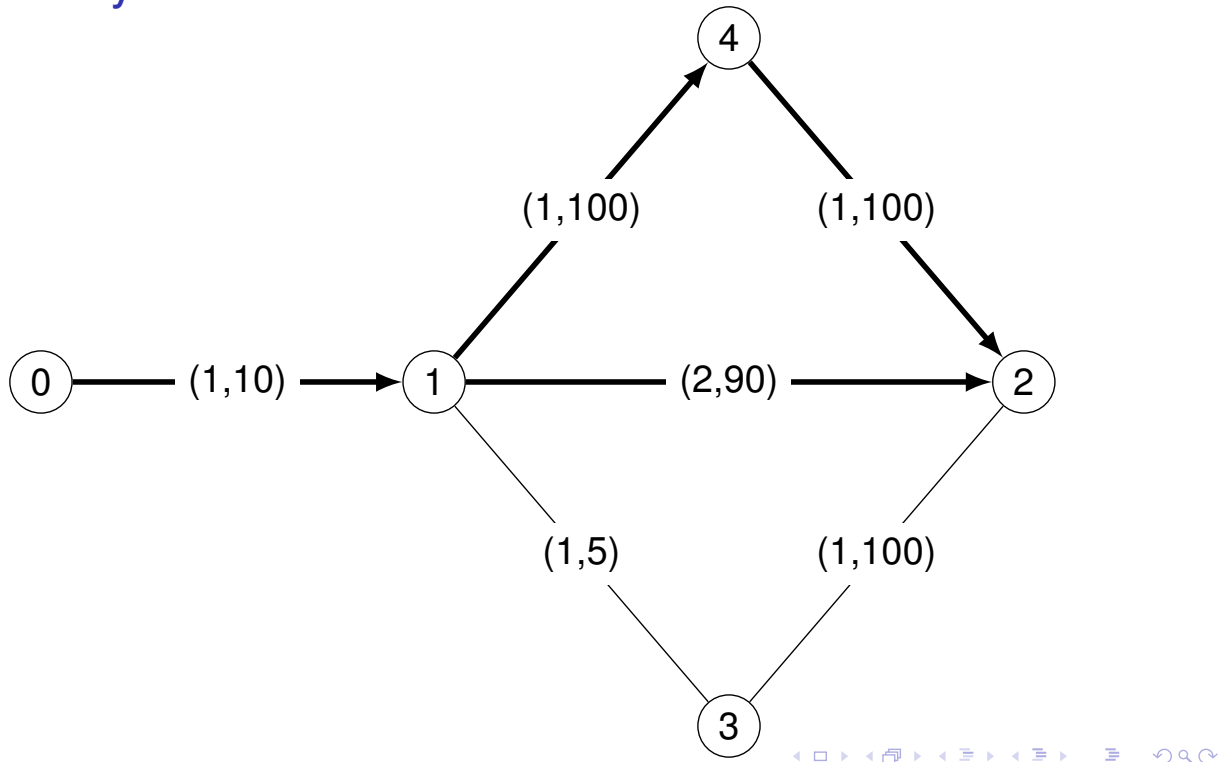
$$\begin{aligned}\mathbf{P}_{\text{Dijkstra}}(0, 2) &= \{(0, 1, 2), (0, 1, 4, 2)\} \\ \mathbf{P}_{\text{Dijkstra}}(2, 0) &= \{(2, 4, 1, 0)\}\end{aligned}$$

Notice that 0's paths cannot both be implemented with next-hop forwarding since $\mathbf{P}_{\text{Dijkstra}}(1, 2) = \{(1, 4, 2)\}$.

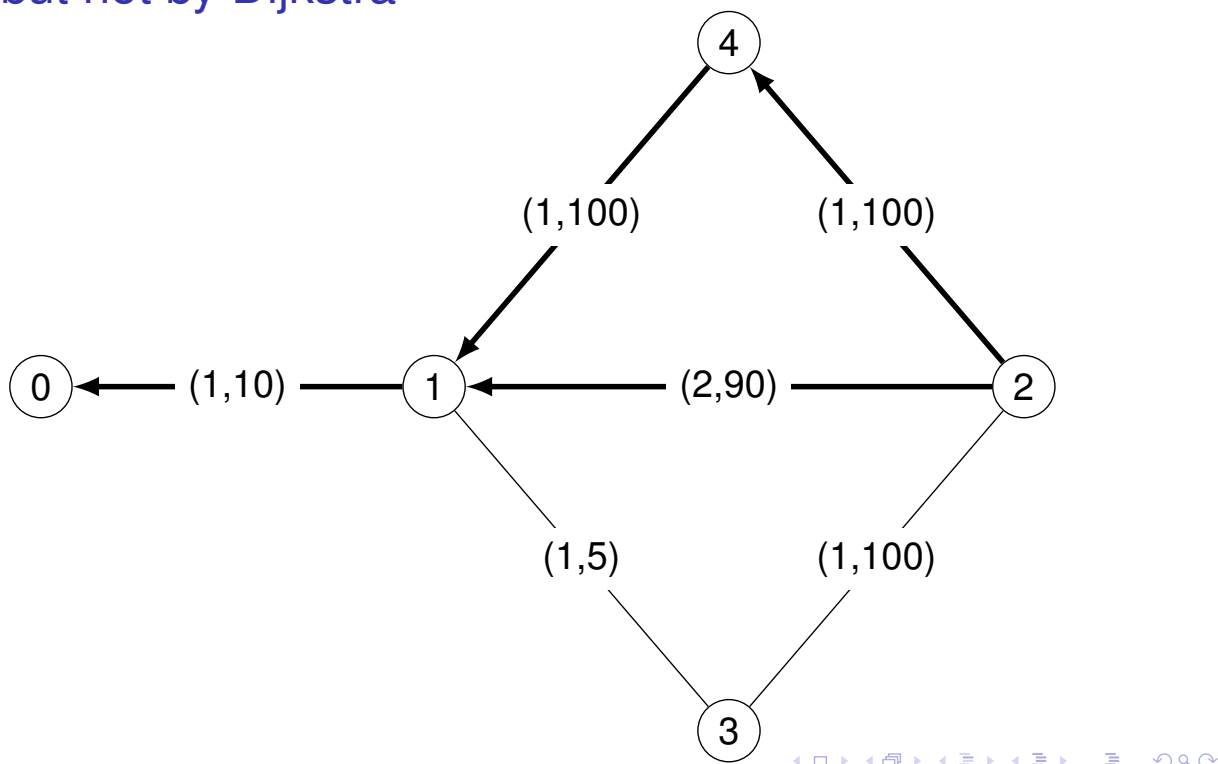
Paths computed by **distributed Bellman-Ford**

$$\begin{aligned}\mathbf{P}_{\text{Bellman}}(0, 2) &= \{(0, 1, 4, 2)\} \\ \mathbf{P}_{\text{Bellman}}(2, 0) &= \{(2, 1, 0), (2, 4, 1, 0)\}\end{aligned}$$

Optimal paths from 0 to 2. Computed by Dijkstra but not by Bellman-Ford



Optimal paths from 2 to 1. Computed by Bellman-Ford but not by Dijkstra



How can we understand this (algebraically)?

The Algorithm to Algebra (A2A) method

$$\left(\begin{array}{c} \text{original metric} \\ + \\ \text{complex algorithm} \end{array} \right) \rightarrow \left(\begin{array}{c} \text{modified metric} \\ + \\ \text{matrix equations (generic algorithm)} \end{array} \right)$$

Preview

- We can add paths explicitly to the widest shortest-path semiring to obtain a new algebra.
- We will see that distributivity does not hold for this algebra.
- Why? We will see that it is because min is not cancellative! ($a \min b = a \min c$ does not imply that $b = c$)

Towards a non-classical theory of algebraic path finding

We need theory that can accept algebras that violate distributivity.

Global optimality

$$\mathbf{A}^*(i, j) = \bigoplus_{p \in P(i, j)} w(p),$$

Left local optimality (distributed Bellman-Ford)

$$\mathbf{L} = (\mathbf{A} \otimes \mathbf{L}) \oplus \mathbf{I}.$$

Right local optimality (Dijkstra's Algorithm)

$$\mathbf{R} = (\mathbf{R} \otimes \mathbf{A}) \oplus \mathbf{I}.$$

Embrace the fact that all three notions can be distinct.

Lectures 2, 3

- Semigroups
- A few important semigroup properties
- Semigroup and partial orders

Semigroups

Semigroup

A **semigroup** (S, \bullet) is a non-empty set S with a binary operation such that

$$\text{AS associative} \equiv \forall a, b, c \in S, a \bullet (b \bullet c) = (a \bullet b) \bullet c$$

Important Assumption — We will ignore trivial semigroups

We will implicitly assume that $2 \leq |S|$.

Note

Many useful binary operations are not semigroup operations. For example, (\mathbb{R}, \bullet) , where $a \bullet b \equiv (a + b)/2$.

Some Important Semigroup Properties

ID	identity	$\equiv \exists \alpha \in S, \forall a \in S, a = \alpha \bullet a = a \bullet \alpha$
AN	annihilator	$\equiv \exists \omega \in S, \forall a \in S, \omega = \omega \bullet a = a \bullet \omega$
CM	commutative	$\equiv \forall a, b \in S, a \bullet b = b \bullet a$
SL	selective	$\equiv \forall a, b \in S, a \bullet b \in \{a, b\}$
IP	idempotent	$\equiv \forall a \in S, a \bullet a = a$

A semigroup with an identity is called a **monoid**.

Note that

$$\text{SL}(S, \bullet) \implies \text{IP}(S, \bullet)$$

Navigation icons: back, forward, search, etc.

A few concrete semigroups

S	\bullet	description	α	ω	CM	SL	IP
S	left	$x \text{ left } y = x$				*	*
S	right	$x \text{ right } y = y$				*	*
S^*	\cdot	concatenation	ϵ				
S^+	\cdot	concatenation					
$\{t, f\}$	\wedge	conjunction	t	f	*	*	*
$\{t, f\}$	\vee	disjunction	f	t	*	*	*
\mathbb{N}	min	minimum		0	*	*	*
\mathbb{N}	max	maximum	0		*	*	*
2^W	\cup	union	$\{\}$	W	*		*
2^W	\cap	intersection	W	$\{\}$	*		*
$\text{fin}(2^U)$	\cup	union	$\{\}$		*		*
$\text{fin}(2^U)$	\cap	intersection		$\{\}$	*		*
\mathbb{N}	+	addition	0		*		
\mathbb{N}	\times	multiplication	1	0	*		

W a finite set, U an infinite set. For set Y , $\text{fin}(Y) \equiv \{X \in Y \mid X \text{ is finite}\}$

A few abstract semigroups

S	\bullet	description	α	ω	CM	SL	IP
2^U	\cup	union	$\{\}$	U	\star		\star
2^U	\cap	intersection	U	$\{\}$	\star		\star
$2^{U \times U}$	\bowtie	relational join	\mathcal{I}_U	$\{\}$			
$X \rightarrow X$	\circ	composition	$\lambda x.x$				

U an infinite set

$$X \bowtie Y \equiv \{(x, z) \in U \times U \mid \exists y \in U, (x, y) \in X \wedge (y, z) \in Y\}$$

$$\mathcal{I}_U \equiv \{(u, u) \mid u \in U\}$$

subsemigroup

Suppose (S, \bullet) is a semigroup and $T \subseteq S$. If T is closed w.r.t \bullet (that is, $\forall x, y \in T, x \bullet y \in T$), then (T, \bullet) is a **subsemigroup** of S .

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Order Relations

We are interested in order relations $\leq \subseteq S \times S$

Definition (Important Order Properties)

RX	reflexive	$\equiv a \leq a$
TR	transitive	$\equiv a \leq b \wedge b \leq c \rightarrow a \leq c$
AY	antisymmetric	$\equiv a \leq b \wedge b \leq a \rightarrow a = b$
TO	total	$\equiv a \leq b \vee b \leq a$

	pre-order	partial order	preference order	total order
RX	\star	\star	\star	\star
TR	\star	\star	\star	\star
AY		\star		\star
TO			\star	\star

Navigation icons: back, forward, search, etc.

Canonical Pre-order of a Commutative Semigroup

Definition (Canonical pre-orders)

$$\begin{aligned}a \trianglelefteq_{\bullet}^R b &\equiv \exists c \in S : b = a \bullet c \\a \trianglelefteq_{\bullet}^L b &\equiv \exists c \in S : a = b \bullet c\end{aligned}$$

Lemma (Sanity check)

Associativity of \bullet implies that these relations are transitive.

Proof.

Note that $a \trianglelefteq_{\bullet}^R b$ means $\exists c_1 \in S : b = a \bullet c_1$, and $b \trianglelefteq_{\bullet}^R c$ means $\exists c_2 \in S : c = b \bullet c_2$. Letting $c_3 = c_1 \bullet c_2$ we have $c = b \bullet c_2 = (a \bullet c_1) \bullet c_2 = a \bullet (c_1 \bullet c_2) = a \bullet c_3$. That is, $\exists c_3 \in S : c = a \bullet c_3$, so $a \trianglelefteq_{\bullet}^R c$. The proof for $\trianglelefteq_{\bullet}^L$ is similar. □

Canonically Ordered Semigroup

Definition (Canonically Ordered Semigroup)

A commutative semigroup (S, \bullet) is **canonically ordered** when $a \trianglelefteq_{\bullet}^R c$ and $a \trianglelefteq_{\bullet}^L c$ are partial orders.

Definition (Groups)

A monoid is a **group** if for every $a \in S$ there exists a $a^{-1} \in S$ such that $a \bullet a^{-1} = a^{-1} \bullet a = \alpha$.

Canonically Ordered Semigroups vs. Groups

Lemma (THE BIG DIVIDE)

Only a trivial group is canonically ordered.

Proof.

If $a, b \in S$, then $a = \alpha_\bullet \bullet a = (b \bullet b^{-1}) \bullet a = b \bullet (b^{-1} \bullet a) = b \bullet c$, for $c = b^{-1} \bullet a$, so $a \leq_\bullet^L b$. In a similar way, $b \leq_\bullet^R a$. Therefore $a = b$.

Natural Orders

Definition (Natural orders)

Let (S, \bullet) be a semigroup.

$$\begin{aligned} a \leqslant_{\bullet}^L b &\equiv a = a \bullet b \\ a \leqslant_{\bullet}^R b &\equiv b = a \bullet b \end{aligned}$$

Lemma

If \bullet is commutative and idempotent, then $a \underline{\leq}_{\bullet}^D b \iff a \leq_{\bullet}^D b$, for $D \in \{R, L\}$.

Proof.

$$\begin{aligned} a \trianglelefteq_{\bullet}^R b &\iff b = a \bullet c = (a \bullet a) \bullet c = a \bullet (a \bullet c) \\ &= a \bullet b \iff a \leq_{\bullet}^R b \\ a \trianglelefteq_{\bullet}^L b &\iff a = b \bullet c = (b \bullet b) \bullet c = b \bullet (b \bullet c) \\ &= b \bullet a = a \bullet b \iff a \leq_{\bullet}^L b \end{aligned}$$

Special elements and natural orders

Lemma (Natural Bounds)

- If α exists, then for all a , $a \leq_L \alpha$ and $\alpha \leq_R a$
- If ω exists, then for all a , $\omega \leq_L a$ and $a \leq_R \omega$
- If α and ω exist, then S is **bounded**.

$$\begin{array}{ccc} \omega & \leq_{\bullet}^L & a \\ \alpha & \leq_{\bullet}^R & a \end{array}$$

Remark (Thanks to Iljitsch van Beijnum)

Note that this means for $(\min, +)$ we have

$$\begin{array}{cc} 0 & \leq_{\min}^L a & \leq_{\min}^L \infty \\ \infty & \leq_{\min}^R a & \leq_{\min}^R 0 \end{array}$$

and still say that this is bounded, even though one might argue with the terminology!

Examples of special elements

S	\bullet	α	ω	\preceq_{\bullet}^L	\preceq_{\bullet}^R
\mathbb{N}^{∞}	min	∞	0	\preceq	\succeq
$\mathbb{N}^{-\infty}$	max	0	$-\infty$	\succeq	\preceq
$\mathcal{P}(W)$	\cup	$\{ \}$	W	\subseteq	\supseteq
$\mathcal{P}(W)$	\cap	W	$\{ \}$	\supseteq	\subseteq

Property Management

Lemma

Let $D \in \{R, L\}$.

- ① $\text{IP}(S, \bullet) \iff \text{RX}(S, \leq^D)$
- ② $\text{CM}(S, \bullet) \implies \text{AY}(S, \leq^D)$
- ③ $\text{AS}(S, \bullet) \implies \text{TR}(S, \leq^D)$
- ④ $\text{CM}(S, \bullet) \implies (\text{SL}(S, \bullet) \iff \text{TO}(S, \leq^D))$

Proof.

- ① $a \leq^D a \iff a = a \bullet a,$
- ② $a \leq^L b \wedge b \leq^L a \iff a = a \bullet b \wedge b = b \bullet a \implies a = b$
- ③ $a \leq^L b \wedge b \leq^L c \iff a = a \bullet b \wedge b = b \bullet c \implies a = a \bullet (b \bullet c) = (a \bullet b) \bullet c = a \bullet c \implies a \leq^L c$
- ④ $a = a \bullet b \vee b = a \bullet b \iff a \leq^L b \vee b \leq^L a$

□

Bounds

Suppose (S, \leq) is a partially ordered set.

greatest lower bound

For $a, b \in S$, the element $c \in S$ is the greatest lower bound of a and b , written $c = a \text{ glb } b$, if it is a lower bound ($c \leq a$ and $c \leq b$), and for every $d \in S$ with $d \leq a$ and $d \leq b$, we have $d \leq c$.

least upper bound

For $a, b \in S$, the element $c \in S$ is the least upper bound of a and b , written $c = a \text{ lub } b$, if it is an upper bound ($a \leq c$ and $b \leq c$), and for every $d \in S$ with $a \leq d$ and $b \leq d$, we have $c \leq d$.

Semi-lattices

Suppose (S, \leq) is a partially ordered set.

meet-semilattice

S is a meet-semilattice if $a \text{ glb } b$ exists for each $a, b \in S$.

join-semilattice

S is a join-semilattice if $a \text{ lub } b$ exists for each $a, b \in S$.

Fun Facts

Fact 1

Suppose (S, \bullet) is a commutative and idempotent semigroup.

- (S, \leq^L) is a meet-semilattice with $a \text{ glb } b = a \bullet b$.
- (S, \leq^R) is a join-semilattice with $a \text{ lub } b = a \bullet b$.

Fact 2

Suppose (S, \leq) is a partially ordered set.

- If (S, \leq) is a meet-semilattice, then (S, glb) is a commutative and idempotent semigroup.
- If (S, \leq) is a join-semilattice, then (S, lub) is a commutative and idempotent semigroup.

That is, semi-lattices represent the same class of structures as commutative and idempotent semigroups.

Lecture 3

- Semirings
- Matrix semirings
- Shortest paths
- Minimax

Bi-semigroups and Pre-Semirings

(S, \oplus, \otimes) is a **bi-semigroup** when

- (S, \oplus) is a semigroup
- (S, \otimes) is a semigroup

(S, \oplus, \otimes) is a **pre-semiring** when

- (S, \oplus, \otimes) is a bi-semigroup
- \oplus is commutative

and left- and right-distributivity hold,

$$\text{LD} : a \otimes (b \oplus c) = (a \otimes b) \oplus (a \otimes c)$$

$$\text{RD} : (a \oplus b) \otimes c = (a \otimes c) \oplus (b \otimes c)$$

Semirings

$(S, \oplus, \otimes, \bar{0}, \bar{1})$ is a **semiring** when

- (S, \oplus, \otimes) is a pre-semiring
- $(S, \oplus, \bar{0})$ is a (commutative) monoid
- $(S, \otimes, \bar{1})$ is a monoid
- $\bar{0}$ is an annihilator for \otimes

Examples

Pre-semirings

name	S	$\oplus,$	\otimes	$\bar{0}$	$\bar{1}$
min_plus	\mathbb{N}	min	+		0
max_min	\mathbb{N}	max	min	0	

Semirings

name	S	$\oplus,$	\otimes	$\bar{0}$	$\bar{1}$
sp	\mathbb{N}^∞	min	+	∞	0
bw	\mathbb{N}^∞	max	min	0	∞

Note the sloppiness — the symbols $+$, \max , and \min in the two tables represent different functions....

How about (max, +)?

Pre-semiring

name	S	\oplus	\otimes	$\bar{0}$	$\bar{1}$
max_plus	\mathbb{N}	max	+	0	0

- What about “ $\bar{0}$ is an annihilator for \otimes ”? No!

Fix that ...

name	S	\oplus	\otimes	$\bar{0}$	$\bar{1}$
max_plus ^{-∞}	$\mathbb{N} \uplus \{-\infty\}$	max	+	$-\infty$	0

Navigation icons: back, forward, search, etc.

Matrix Semirings

- $(S, \oplus, \otimes, \bar{0}, \bar{1})$ a semiring
- Define the semiring of $n \times n$ -matrices over S : $(\mathbb{M}_n(S), \oplus, \otimes, \mathbf{J}, \mathbf{I})$

\oplus and \otimes

$$(\mathbf{A} \oplus \mathbf{B})(i, j) = \mathbf{A}(i, j) \oplus \mathbf{B}(i, j)$$

$$(\mathbf{A} \otimes \mathbf{B})(i, j) = \bigoplus_{1 \leq q \leq n} \mathbf{A}(i, q) \otimes \mathbf{B}(q, j)$$

\mathbf{J} and \mathbf{I}

$$\mathbf{J}(i, j) = \bar{0}$$

$$\mathbf{I}(i, j) = \begin{cases} \bar{1} & (\text{if } i = j) \\ \bar{0} & (\text{otherwise}) \end{cases}$$

Associativity

$$\mathbf{A} \otimes (\mathbf{B} \otimes \mathbf{C}) = (\mathbf{A} \otimes \mathbf{B}) \otimes \mathbf{C}$$

$$\begin{aligned}
 & (\mathbf{A} \otimes (\mathbf{B} \otimes \mathbf{C}))(i, j) \\
 = & \bigoplus_{1 \leq u \leq n} \mathbf{A}(i, u) \otimes (\mathbf{B} \otimes \mathbf{C})(u, j) & (\text{def } \rightarrow) \\
 = & \bigoplus_{1 \leq u \leq n} \mathbf{A}(i, u) \otimes \left(\bigoplus_{1 \leq v \leq n} \mathbf{B}(u, v) \otimes \mathbf{C}(v, j) \right) & (\text{def } \rightarrow) \\
 = & \bigoplus_{1 \leq u \leq n} \bigoplus_{1 \leq v \leq n} \mathbf{A}(i, u) \otimes (\mathbf{B}(u, v) \otimes \mathbf{C}(v, j)) & (\text{LD}) \\
 = & \bigoplus_{1 \leq v \leq n} \bigoplus_{1 \leq u \leq n} (\mathbf{A}(i, u) \otimes \mathbf{B}(u, v)) \otimes \mathbf{C}(v, j) & (\text{AS, CM}) \\
 = & \bigoplus_{1 \leq v \leq n} \left(\bigoplus_{1 \leq u \leq n} \mathbf{A}(i, u) \otimes \mathbf{B}(u, v) \right) \otimes \mathbf{C}(v, j) & (\text{RD}) \\
 = & \bigoplus_{1 \leq v \leq n} (\mathbf{A} \otimes \mathbf{B})(i, v) \otimes \mathbf{C}(v, j) & (\text{def } \leftarrow) \\
 = & ((\mathbf{A} \otimes \mathbf{B}) \otimes \mathbf{C})(i, j) & (\text{def } \leftarrow)
 \end{aligned}$$

Left Distributivity

$$\mathbf{A} \otimes (\mathbf{B} \oplus \mathbf{C}) = (\mathbf{A} \otimes \mathbf{B}) \oplus (\mathbf{A} \otimes \mathbf{C})$$

$$\begin{aligned}
 & (\mathbf{A} \otimes (\mathbf{B} \oplus \mathbf{C}))(i, j) \\
 = & \bigoplus_{1 \leq q \leq n} \mathbf{A}(i, q) \otimes (\mathbf{B} \oplus \mathbf{C})(q, j) & (\text{def } \rightarrow) \\
 = & \bigoplus_{1 \leq q \leq n} \mathbf{A}(i, q) \otimes (\mathbf{B}(q, j) \oplus \mathbf{C}(q, j)) & (\text{def } \rightarrow) \\
 = & \bigoplus_{1 \leq q \leq n} (\mathbf{A}(i, q) \otimes \mathbf{B}(q, j)) \oplus (\mathbf{A}(i, q) \otimes \mathbf{C}(q, j)) & (\text{LD}) \\
 = & \left(\bigoplus_{1 \leq q \leq n} \mathbf{A}(i, q) \otimes \mathbf{B}(q, j) \right) \oplus \left(\bigoplus_{1 \leq q \leq n} \mathbf{A}(i, q) \otimes \mathbf{C}(q, j) \right) & (\text{AS, CM}) \\
 = & ((\mathbf{A} \otimes \mathbf{B}) \oplus (\mathbf{A} \otimes \mathbf{C}))(i, j) & (\text{def } \leftarrow)
 \end{aligned}$$

Matrix encoding path problems

- $(S, \oplus, \otimes, \bar{0}, \bar{1})$ a semiring
- $G = (V, E)$ a directed graph
- $w \in E \rightarrow S$ a weight function

Path weight

The weight of a path $p = i_1, i_2, i_3, \dots, i_k$ is

$$w(p) = w(i_1, i_2) \otimes w(i_2, i_3) \otimes \dots \otimes w(i_{k-1}, i_k).$$

The empty path is given the weight $\bar{1}$.

Adjacency matrix \mathbf{A}

$$\mathbf{A}(i, j) = \begin{cases} w(i, j) & \text{if } (i, j) \in E, \\ \bar{0} & \text{otherwise} \end{cases}$$

The general problem of finding globally optimal path weights

Given an adjacency matrix \mathbf{A} , find \mathbf{A}^* such that for all $i, j \in V$

$$\mathbf{A}^*(i, j) = \bigoplus_{p \in \pi(i, j)} w(p)$$

where $\pi(i, j)$ represents the set of all paths from i to j .

How can we solve this problem?

Stability

- $(S, \oplus, \otimes, \bar{0}, \bar{1})$ a semiring

$a \in S$, define powers a^k

$$\begin{aligned}a^0 &= \bar{1} \\ a^{k+1} &= a \otimes a^k\end{aligned}$$

Closure, a^*

$$\begin{aligned}a^{(k)} &= a^0 \oplus a^1 \oplus a^2 \oplus \dots \oplus a^k \\ a^* &= a^0 \oplus a^1 \oplus a^2 \oplus \dots \oplus a^k \oplus \dots\end{aligned}$$

Definition (q stability)

If there exists a q such that $a^{(q)} = a^{(q+1)}$, then a is **q -stable**. By induction: $\forall t, 0 \leq t, a^{(q+t)} = a^{(q)}$. Therefore, $a^* = a^{(q)}$.

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Matrix methods

Matrix powers, \mathbf{A}^k

$$\begin{aligned}\mathbf{A}^0 &= \mathbf{I} \\ \mathbf{A}^{k+1} &= \mathbf{A} \otimes \mathbf{A}^k\end{aligned}$$

Closure, \mathbf{A}^*

$$\begin{aligned}\mathbf{A}^{(k)} &= \mathbf{I} \oplus \mathbf{A}^1 \oplus \mathbf{A}^2 \oplus \dots \oplus \mathbf{A}^k \\ \mathbf{A}^* &= \mathbf{I} \oplus \mathbf{A}^1 \oplus \mathbf{A}^2 \oplus \dots \oplus \mathbf{A}^k \oplus \dots\end{aligned}$$

Note: \mathbf{A}^* might not exist. Why?

Navigation icons

Matrix methods can compute optimal path weights

- Let $\pi(i, j)$ be the set of paths from i to j .
- Let $\pi^k(i, j)$ be the set of paths from i to j with exactly k arcs.
- Let $\pi^{(k)}(i, j)$ be the set of paths from i to j with at most k arcs.

Theorem

$$\begin{aligned}(1) \quad \mathbf{A}^k(i, j) &= \bigoplus_{p \in \pi^k(i, j)} w(p) \\(2) \quad \mathbf{A}^{(k)}(i, j) &= \bigoplus_{p \in \pi^{(k)}(i, j)} w(p) \\(3) \quad \mathbf{A}^*(i, j) &= \bigoplus_{p \in \pi(i, j)} w(p)\end{aligned}$$

Warning again: for some semirings the expression $\mathbf{A}^*(i, j)$ might not be well-defined. Why?

Proof of (1)

By induction on k . Base Case: $k = 0$.

$$\pi^0(i, i) = \{\epsilon\},$$

$$\text{so } \mathbf{A}^0(i, i) = \mathbf{I}(i, i) = \bar{1} = w(\epsilon).$$

And $i \neq j$ implies $\pi^0(i, j) = \{\}$. By convention

$$\bigoplus_{p \in \{\}} w(p) = \bar{0} = \mathbf{I}(i, j).$$

Proof of (1)

Induction step.

$$\begin{aligned}
 \mathbf{A}^{k+1}(i, j) &= (\mathbf{A} \otimes \mathbf{A}^k)(i, j) \\
 &= \bigoplus_{1 \leq q \leq n} \mathbf{A}(i, q) \otimes \mathbf{A}^k(q, j) \\
 &= \bigoplus_{1 \leq q \leq n} \mathbf{A}(i, q) \otimes \left(\bigoplus_{p \in \pi^k(q, j)} w(p) \right) \\
 &= \bigoplus_{1 \leq q \leq n} \bigoplus_{p \in \pi^k(q, j)} \mathbf{A}(i, q) \otimes w(p) \\
 &= \bigoplus_{(i, q) \in E} \bigoplus_{p \in \pi^k(q, j)} w(i, q) \otimes w(p) \\
 &= \bigoplus_{p \in \pi^{k+1}(i, j)} w(p)
 \end{aligned}$$

Fun Facts

Fact 3

If $\bar{1}$ is an annihilator for \oplus , then every $a \in S$ is 0-stable!

Fact 4

If S is 0-stable, then $\mathbb{M}_n(S)$ is $(n - 1)$ -stable. That is,

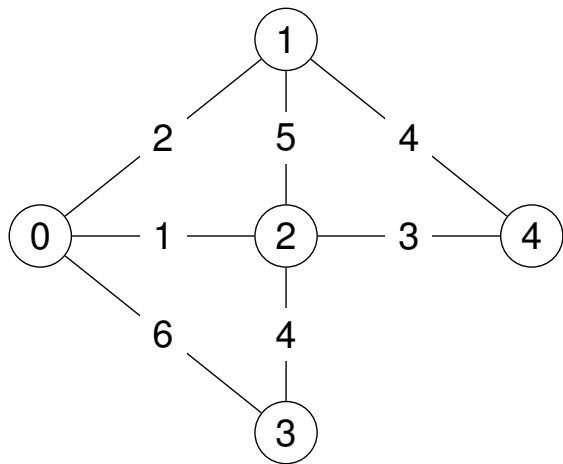
$$\mathbf{A}^* = \mathbf{A}^{(n-1)} = \mathbf{I} \oplus \mathbf{A}^1 \oplus \mathbf{A}^2 \oplus \dots \oplus \mathbf{A}^{n-1}$$

Why? Because we can ignore paths with loops.

$$(a \otimes c \otimes b) \oplus (a \otimes b) = a \otimes (\bar{1} \oplus c) \otimes b = a \otimes \bar{1} \otimes b = a \otimes b$$

Think of c as the weight of a loop in a path with weight $a \otimes b$.

Shortest paths example, $(\mathbb{N}^\infty, \min, +)$



The adjacency matrix

$$\mathbf{A} = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} \infty & 2 & 1 & 6 & \infty \\ 2 & \infty & 5 & \infty & 4 \\ 1 & 5 & \infty & 4 & 3 \\ 6 & \infty & 4 & \infty & \infty \\ \infty & 4 & 3 & \infty & \infty \end{bmatrix} \end{matrix}$$

Note that the longest shortest path is $(1, 0, 2, 3)$ of length 3 and weight 7.

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$(\min, +)$ example

Our theorem tells us that $\mathbf{A}^* = \mathbf{A}^{(n-1)} = \mathbf{A}^{(4)}$

$$\mathbf{A}^* = \mathbf{A}^{(4)} = \mathbf{I} \min \mathbf{A} \min \mathbf{A}^2 \min \mathbf{A}^3 \min \mathbf{A}^4 = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 0 & 2 & 1 & 5 & 4 \\ 2 & 0 & 3 & 7 & 4 \\ 1 & 3 & 0 & 4 & 3 \\ 5 & 7 & 4 & 0 & 7 \\ 4 & 4 & 3 & 7 & 0 \end{bmatrix} \end{matrix}$$

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(min, +) example

$$\begin{aligned}
 \mathbf{A} &= \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} \infty & \underline{2} & \underline{1} & 6 & \infty \\ \underline{2} & \infty & 5 & \infty & \underline{4} \\ \underline{1} & 5 & \infty & \underline{4} & \underline{3} \\ 6 & \infty & \underline{4} & \infty & \infty \\ \infty & \underline{4} & \underline{3} & \infty & \infty \end{bmatrix} \end{matrix} & \mathbf{A}^3 = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 8 & 4 & 3 & 8 & 10 \\ 4 & 8 & 7 & \underline{7} & 6 \\ 3 & 7 & 8 & 6 & 5 \\ 8 & \underline{7} & 6 & 11 & 10 \\ 10 & 6 & 5 & 10 & 12 \end{bmatrix} \end{matrix} \\
\mathbf{A}^2 &= \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 2 & 6 & 7 & \underline{5} & \underline{4} \\ 6 & 4 & \underline{3} & 8 & 8 \\ 7 & \underline{3} & 2 & 7 & 9 \\ \underline{5} & 8 & 7 & 8 & \underline{7} \\ \underline{4} & 8 & 9 & \underline{7} & 6 \end{bmatrix} \end{matrix} & \mathbf{A}^4 = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 4 & 8 & 9 & 7 & 6 \\ 8 & 6 & 5 & 10 & 10 \\ 9 & 5 & 4 & 9 & 11 \\ 7 & 10 & 9 & 10 & 9 \\ 6 & 10 & 11 & 9 & 8 \end{bmatrix} \end{matrix}
\end{aligned}$$

First appearance of final value is in red and underlined. Remember: we are looking at all paths of a given length, even those with cycles!

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\mathbf{A} vs $\mathbf{A} \oplus \mathbf{I}$

Lemma

If \oplus is idempotent, then

$$(\mathbf{A} \oplus \mathbf{I})^k = \mathbf{A}^{(k)}.$$

Proof. Base case: When $k = 0$ both expressions are \mathbf{I} .

Assume $(\mathbf{A} \oplus \mathbf{I})^k = \mathbf{A}^{(k)}$. Then

$$\begin{aligned}
 (\mathbf{A} \oplus \mathbf{I})^{k+1} &= (\mathbf{A} \oplus \mathbf{I})(\mathbf{A} \oplus \mathbf{I})^k \\
 &= (\mathbf{A} \oplus \mathbf{I})\mathbf{A}^{(k)} \\
 &= \mathbf{A}\mathbf{A}^{(k)} \oplus \mathbf{A}^{(k)} \\
 &= \mathbf{A}(\mathbf{I} \oplus \mathbf{A} \oplus \dots \oplus \mathbf{A}^k) \oplus \mathbf{A}^{(k)} \\
 &= \mathbf{A} \oplus \mathbf{A}^2 \oplus \dots \oplus \mathbf{A}^{k+1} \oplus \mathbf{A}^{(k)} \\
 &= \mathbf{A}^{k+1} \oplus \mathbf{A}^{(k)} \\
 &= \mathbf{A}^{(k+1)}
 \end{aligned}$$

Navigation icons: back, forward, search, etc.

back to (min, +) example

$$\begin{aligned}
 (\mathbf{A} \oplus \mathbf{I})^1 &= \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 0 & 2 & 1 & 6 & \infty \\ 2 & 0 & 5 & \infty & 4 \\ 1 & 5 & 0 & 4 & 3 \\ 6 & \infty & 4 & 0 & \infty \\ \infty & 4 & 3 & \infty & 0 \end{bmatrix} \end{matrix} \quad (\mathbf{A} \oplus \mathbf{I})^3 = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 0 & 2 & 1 & 5 & 4 \\ 2 & 0 & 3 & 7 & 4 \\ 1 & 3 & 0 & 4 & 3 \\ 5 & 7 & 4 & 0 & 7 \\ 4 & 4 & 3 & 7 & 0 \end{bmatrix} \end{matrix} \\
 (\mathbf{A} \oplus \mathbf{I})^2 &= \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 0 & 2 & 1 & 5 & 4 \\ 2 & 0 & 3 & 8 & 4 \\ 1 & 3 & 0 & 4 & 3 \\ 5 & 8 & 4 & 0 & 7 \\ 4 & 4 & 3 & 7 & 0 \end{bmatrix} \end{matrix}
 \end{aligned}$$

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Semigroup properties (so far)

$$\begin{aligned}
 \text{AS}(\mathbf{S}, \bullet) &\equiv \forall a, b, c \in \mathbf{S}, a \bullet (b \bullet c) = (a \bullet b) \bullet c \\
 \text{IID}(\mathbf{S}, \bullet, \alpha) &\equiv \forall a \in \mathbf{S}, a = \alpha \bullet a = a \bullet \alpha \\
 \text{ID}(\mathbf{S}, \bullet) &\equiv \exists \alpha \in \mathbf{S}, \text{IID}(\mathbf{S}, \bullet, \alpha) \\
 \text{IAN}(\mathbf{S}, \bullet, \omega) &\equiv \forall a \in \mathbf{S}, \omega = \omega \bullet a = a \bullet \omega \\
 \text{AN}(\mathbf{S}, \bullet) &\equiv \exists \omega \in \mathbf{S}, \text{IAN}(\mathbf{S}, \bullet, \omega) \\
 \text{CM}(\mathbf{S}, \bullet) &\equiv \forall a, b \in \mathbf{S}, a \bullet b = b \bullet a \\
 \text{SL}(\mathbf{S}, \bullet) &\equiv \forall a, b \in \mathbf{S}, a \bullet b \in \{a, b\} \\
 \text{IP}(\mathbf{S}, \bullet) &\equiv \forall a \in \mathbf{S}, a \bullet a = a \\
 \text{IR}(\mathbf{S}, \bullet) &\equiv \forall s, t \in \mathbf{S}, s \bullet t = t \\
 \text{IL}(\mathbf{S}, \bullet) &\equiv \forall s, t \in \mathbf{S}, s \bullet t = s
 \end{aligned}$$

Recall that is right (IR) and is left (IL) are forced on us by wanting an \Leftrightarrow -rule for $\text{SL}((\mathbf{S}, \bullet) \times (\mathbf{T}, \diamond))$

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Bisemigroup properties (so far)

$$\begin{array}{ll}
 \text{AAS}(\mathcal{S}, \oplus, \otimes) & \equiv \text{AS}(\mathcal{S}, \oplus) \\
 \text{AID}(\mathcal{S}, \oplus, \otimes) & \equiv \text{ID}(\mathcal{S}, \oplus) \\
 \text{ACM}(\mathcal{S}, \oplus, \otimes) & \equiv \text{CM}(\mathcal{S}, \oplus) \\
 \text{MAS}(\mathcal{S}, \oplus, \otimes) & \equiv \text{AS}(\mathcal{S}, \otimes) \\
 \text{MID}(\mathcal{S}, \oplus, \otimes) & \equiv \text{ID}(\mathcal{S}, \otimes) \\
 \text{LD}(\mathcal{S}, \oplus, \otimes) & \equiv \forall a, b, c \in \mathcal{S}, a \otimes (b \oplus c) = (a \otimes b) \oplus (a \otimes c) \\
 \text{RD}(\mathcal{S}, \oplus, \otimes) & \equiv \forall a, b, c \in \mathcal{S}, (a \oplus b) \otimes c = (a \otimes c) \oplus (b \otimes c) \\
 \text{ZA}(\mathcal{S}, \oplus, \otimes) & \equiv \exists \bar{0} \in \mathcal{S}, \text{IID}(\mathcal{S}, \oplus, \bar{0}) \wedge \text{IAN}(\mathcal{S}, \otimes, \bar{0}) \\
 \hline
 \text{OA}(\mathcal{S}, \oplus, \otimes) & \equiv \exists \bar{1} \in \mathcal{S}, \text{IID}(\mathcal{S}, \otimes, \bar{1}) \wedge \text{IAN}(\mathcal{S}, \oplus, \bar{1}) \\
 \text{ASL}(\mathcal{S}, \oplus, \otimes) & \equiv \text{SL}(\mathcal{S}, \oplus) \\
 \text{AIP}(\mathcal{S}, \oplus, \otimes) & \equiv \text{IP}(\mathcal{S}, \oplus)
 \end{array}$$

A Minimax Semiring

$$\text{minimax} \equiv (\mathbb{N}^\infty, \min, \max, \infty, 0)$$

$$17 \min \infty = 17$$

$$17 \max \infty = \infty$$

How can we interpret this?

$$\mathbf{A}^*(i, j) = \min_{p \in \pi(i, j)} \max_{(u, v) \in p} \mathbf{A}(u, v),$$

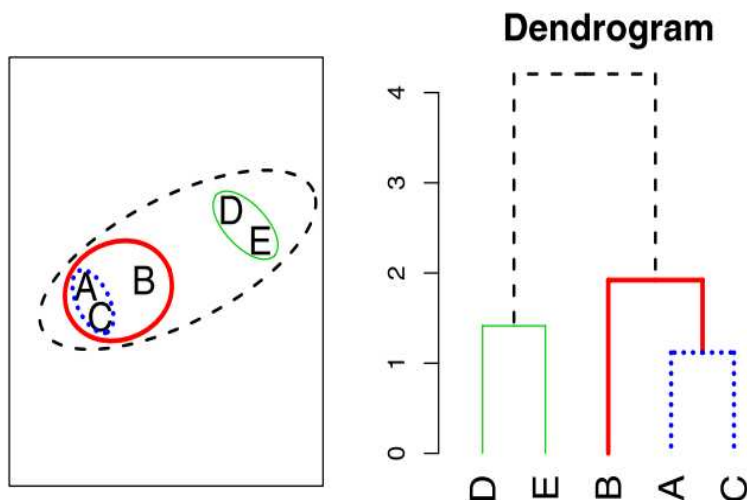
One possible interpretation of Minimax

- Given an adjacency matrix \mathbf{A} over minimax,
- suppose that $\mathbf{A}(i, j) = 0 \Leftrightarrow i = j$,
- suppose that \mathbf{A} is symmetric ($\mathbf{A}(i, j) = \mathbf{A}(j, i)$),
- interpret $\mathbf{A}(i, j)$ as measured dissimilarity of i and j ,
- interpret $\mathbf{A}^*(i, j)$ as inferred dissimilarity of i and j ,

Many uses

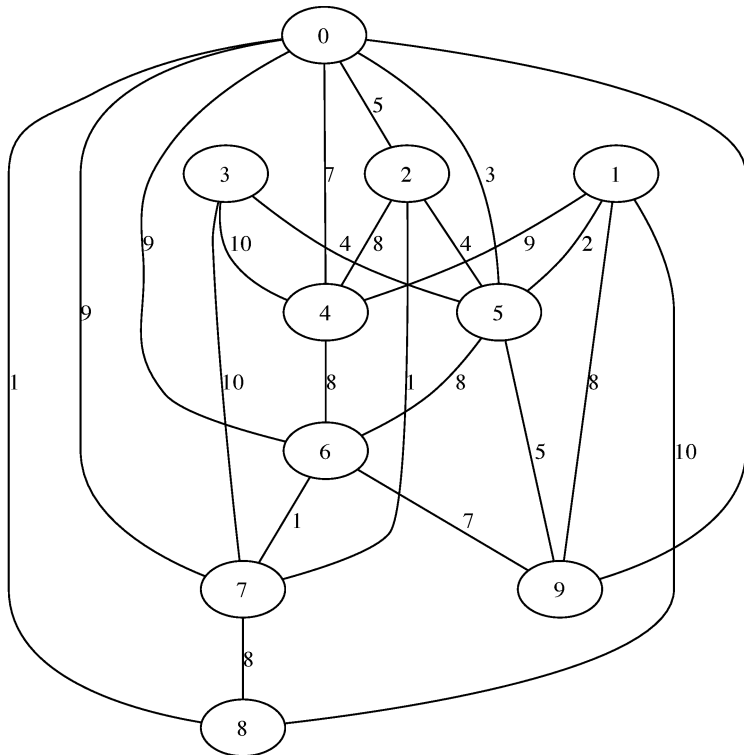
- Hierarchical clustering of large data sets
- Classification in Machine Learning
- Computational phylogenetics
- ...

Dendrograms

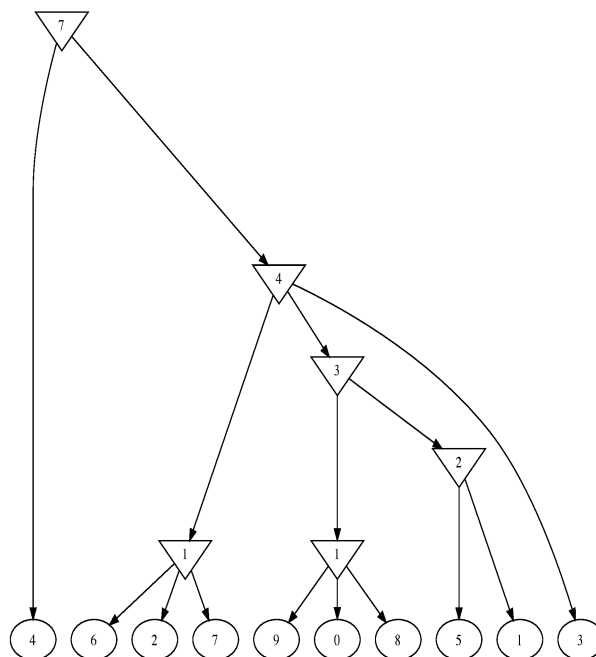


from **Hierarchical Clustering With Prototypes via Minimax Linkage**, Bien and Tibshirani, 2011.

A minimax graph



The solution A^* drawn as a dendrogram



Hierarchical clustering? Why?

Suppose $(Y, \leq, +)$ is a totally ordered with least element 0.

Metric

A metric for set X over $(Y, \leq, +)$ is a function $d \in X \times X \rightarrow Y$ such that

- $\forall x, y \in X, d(x, y) = 0 \Leftrightarrow x = y$
- $\forall x, y \in X, d(x, y) = d(y, x)$
- $\forall x, y, z \in X, d(x, y) \leq d(x, z) + d(z, y)$

Ultrametric

An ultrametric for set X over (Y, \leq) is a function $d \in X \times X \rightarrow Y$ such that

- $\forall x \in X, d(x, x) = 0$
- $\forall x, y \in X, d(x, y) = d(y, x)$
- $\forall x, y, z \in X, d(x, y) \leq d(x, z) \max d(z, y)$

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Fun Facts

Fact 5

If \mathbf{A} is an $n \times n$ symmetric minimax adjacency matrix, then \mathbf{A}^* is a finite ultrametric for $\{0, 1, \dots, n-1\}$ over $(\mathbb{N}^\infty, \leq)$.

Fact 6

Suppose each arc weight is unique. Then the set of arcs

$$\{(i, j) \in E \mid \mathbf{A}(i, j) = \mathbf{A}^*(i, j)\}$$

is a minimum spanning tree.

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A spanning tree derived from \mathbf{A} and \mathbf{A}^*

