

Compiler Construction

Lecture 6: SLR(1) and LR(1)

Jeremy Yallop

jeremy.yallop@cl.cam.ac.uk

Lent 2025

Bottom-up parsing components

Recap &
plan



DFA

SLR(1)

Parsing
with states

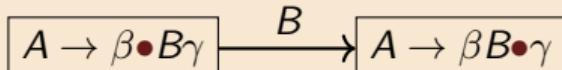
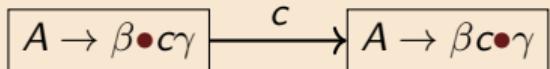
SLR(1)
limits

LR(1)

Configurations $\$ \alpha, w \$$ with actions:

$$\begin{array}{ccc} \$\alpha, xw\$ & \xrightarrow{\text{shift } x} & \$\alpha x, w\$ \\ \$\alpha\beta, w\$ & \xrightarrow{\text{reduce } A \rightarrow \beta} & \$\alpha A, w\$ \end{array}$$

Items $A \rightarrow \beta \bullet \gamma$ with transitions:



A **parsing algorithm**:

$c := \text{NextToken}()$

while true:

$\alpha := \text{the stack}$

if $A \rightarrow \beta \bullet c\gamma \in \delta_G(q_0, \alpha)$

then SHIFT c ; $c := \text{NextToken}()$

if $A \rightarrow \beta \bullet \in \delta_G(q_0, \alpha)$

then REDUCE via $A \rightarrow \beta$

if $S \rightarrow \beta \bullet \in \delta_G(q_0, \alpha)$

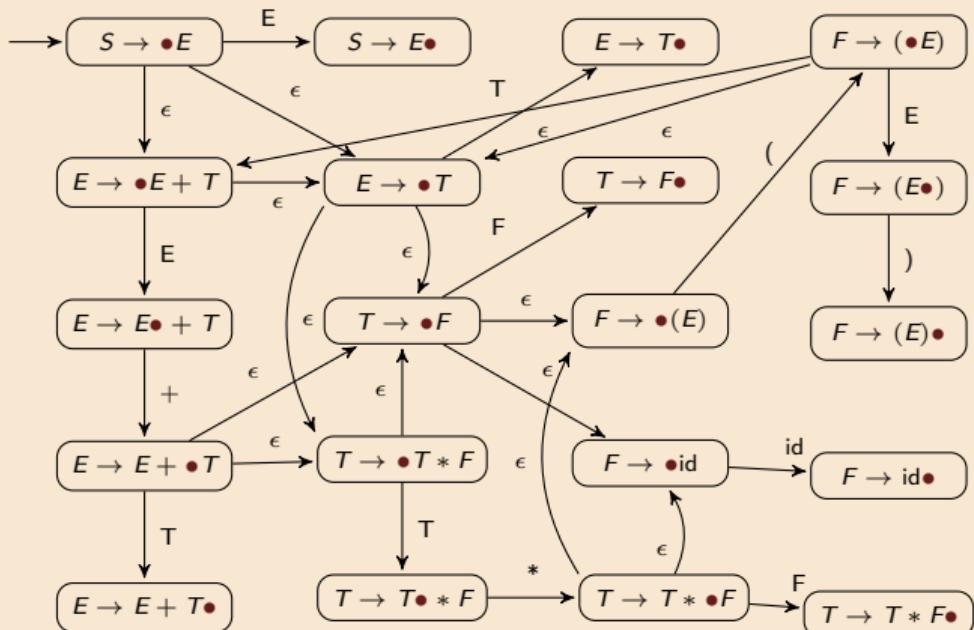
then ACCEPT (if no more input)

if none of the above

then ERROR

non-deterministic

Using the NFA



stack	input
\$	$(x + y) \$$
$\$($	$x + y) \$$
$\$(x$	$+y) \$$
$\$(F$	$+y) \$$
$\$(T$	$+y) \$$
$\$(E$	$+y) \$$
$\$(E +$	$y) \$$
$\$(E + y$	$) \$$
$\$(E + F$	$) \$$
$\$(E + T$	$) \$$
$\$(E$	$) \$$
$\$(E)$	$\$$
$\$F$	$\$$
$\$T$	$\$$
$\$E$	$\$$
$\$S$	$\$$

Example: $\delta_G(S \rightarrow \bullet E, E + F) = \{T \rightarrow F\bullet\}$, so reduce with $T \rightarrow F$.

Example: $\delta_G(S \rightarrow \bullet E, (E) = \{F \rightarrow (E\bullet)\})$, so shift).

Recap & plan



DFA

SLR(1)

Parsing with states

SLR(1) limits

LR(1)

Making the algorithm deterministic

Recap &
plan



DFA

SLR(1)

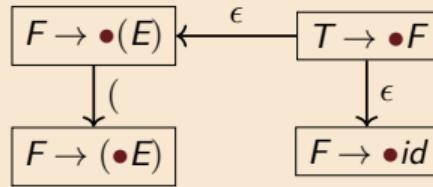
Parsing
with states

SLR(1)
limits

LR(1)

Two sources of **nondeterminism**:

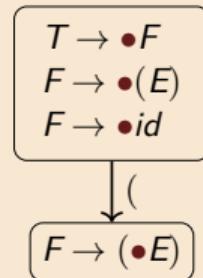
1. The NFA



2. Conflicts

$$\begin{array}{c} \$\alpha E + T, x\$ \\ \xrightarrow{\text{reduce } E \rightarrow E+T} \\ \$\alpha E + T, x\$ \\ \xrightarrow{\text{reduce } E \rightarrow T} \\ \$\alpha E + T, x\$ \\ \xrightarrow{\text{shift } x} \end{array}$$

Solution: convert to a **DFA**



Solution: make a **deterministic choice**

using the **input** (lookahead)
using the **grammar** (FIRST and FOLLOW)

Two approaches: SLR(1) and LR(1)

The DFA

The easy part: NFA → DFA

Recap &
plan

DFA



SLR(1)

Parsing
with states

SLR(1)
limits

LR(1)

Grammar G_2

$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + T \mid T \\ T &\rightarrow T * F \mid F \\ F &\rightarrow (E) \mid \text{id} \end{aligned}$$

$$\begin{aligned} S &\rightarrow \bullet E \\ E &\rightarrow \bullet E + T \\ E &\rightarrow \bullet T \\ T &\rightarrow \bullet T * F \\ T &\rightarrow \bullet F \\ F &\rightarrow \bullet (E) \\ F &\rightarrow \bullet \text{id} \end{aligned}$$

DFA start state = ϵ -closure($\{S \rightarrow \bullet E\}$) =

Transition function:

$$\delta(I, X) = \epsilon\text{-closure}(\{A \rightarrow \alpha X \bullet \beta \mid A \rightarrow \alpha \bullet X \beta \in I\})$$

(**NB**: this is just the powerset/subset construction for converting NFAs to DFAs.)

Some DFA transitions for grammar G_2

Recap &
plan

DFA



SLR(1)

Parsing
with states

SLR(1)
limits

LR(1)

Grammar G'_2

$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + T \mid T \\ T &\rightarrow T * F \mid F \\ F &\rightarrow (E) \mid \text{id} \end{aligned}$$

$F \rightarrow (\bullet E)$

Some DFA transitions for grammar G_2

Recap &
plan

DFA



SLR(1)

Parsing
with states

SLR(1)
limits

LR(1)

Grammar G'_2

$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + T \mid T \\ T &\rightarrow T * F \mid F \\ F &\rightarrow (E) \mid \text{id} \end{aligned}$$
$$\begin{aligned} F &\rightarrow (\bullet E) \\ E &\rightarrow \bullet E + T \\ E &\rightarrow \bullet T \end{aligned}$$

Some DFA transitions for grammar G_2

Recap &
plan

DFA



SLR(1)

Parsing
with states

SLR(1)
limits

LR(1)

Grammar G'_2

$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + T \mid T \\ T &\rightarrow T * F \mid F \\ F &\rightarrow (E) \mid \text{id} \end{aligned}$$
$$\begin{aligned} F &\rightarrow (\bullet E) \\ E &\rightarrow \bullet E + T \\ E &\rightarrow \bullet T \\ T &\rightarrow \bullet T * F \\ T &\rightarrow \bullet F \end{aligned}$$

Some DFA transitions for grammar G_2

Recap &
plan

DFA



SLR(1)

Parsing
with states

SLR(1)
limits

LR(1)

Grammar G'_2

$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + T \mid T \\ T &\rightarrow T * F \mid F \\ F &\rightarrow (E) \mid \text{id} \end{aligned}$$
$$\begin{aligned} F &\rightarrow (\bullet E) \\ E &\rightarrow \bullet E + T \\ E &\rightarrow \bullet T \\ T &\rightarrow \bullet T * F \\ T &\rightarrow \bullet F \\ F &\rightarrow \bullet (E) \\ F &\rightarrow \bullet \text{id} \end{aligned}$$

Some DFA transitions for grammar G_2

Recap &
plan

DFA



SLR(1)

Parsing
with states

SLR(1)
limits

LR(1)

Grammar G'_2

$$\begin{aligned}S &\rightarrow E \\E &\rightarrow E + T \mid T \\T &\rightarrow T * F \mid F \\F &\rightarrow (E) \mid \text{id}\end{aligned}$$
$$\begin{aligned}F &\rightarrow (\bullet E) \\E &\rightarrow \bullet E + T \\E &\rightarrow \bullet T \\T &\rightarrow \bullet T * F \\T &\rightarrow \bullet F \\F &\rightarrow \bullet (E) \\F &\rightarrow \bullet \text{id}\end{aligned}$$

id

 $F \rightarrow \text{id } \bullet$

Some DFA transitions for grammar G_2

Recap &
plan

DFA



SLR(1)

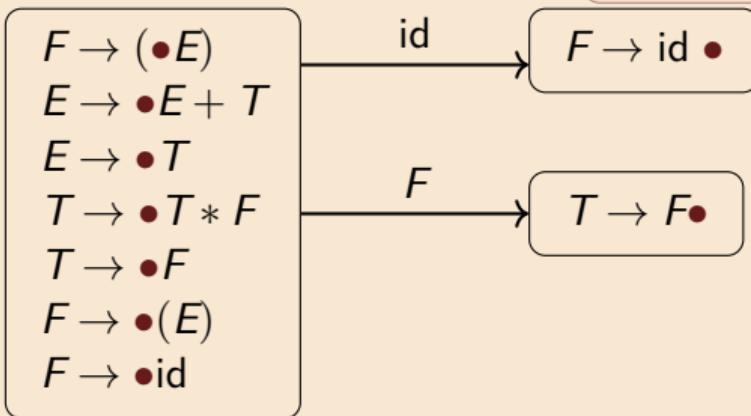
Parsing
with states

SLR(1)
limits

LR(1)

Grammar G'_2

$$\begin{aligned}S &\rightarrow E \\E &\rightarrow E + T \mid T \\T &\rightarrow T * F \mid F \\F &\rightarrow (E) \mid \text{id}\end{aligned}$$



Some DFA transitions for grammar G_2

Recap &
plan

DFA



SLR(1)

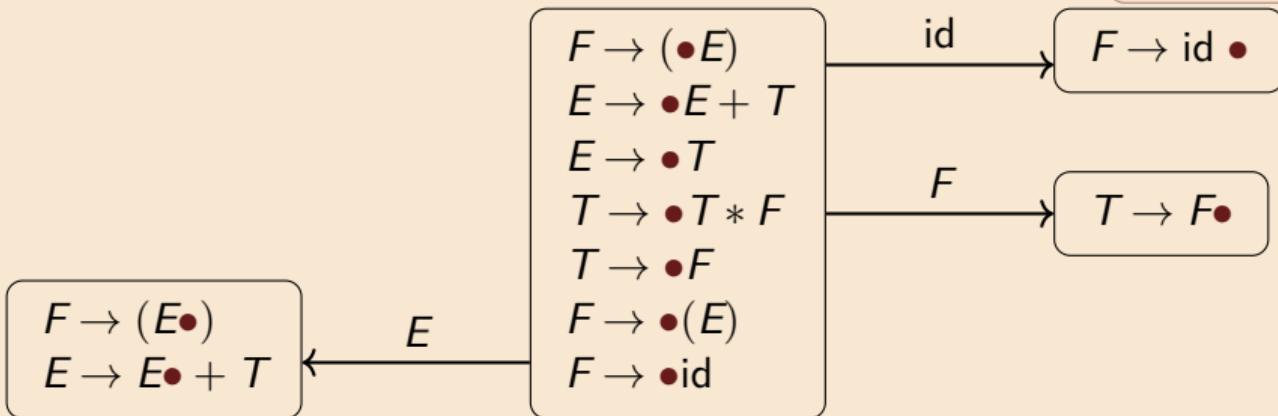
Parsing
with states

SLR(1)
limits

LR(1)

Grammar G'_2

$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + T \mid T \\ T &\rightarrow T * F \mid F \\ F &\rightarrow (E) \mid \text{id} \end{aligned}$$



Some DFA transitions for grammar G_2

Recap &
plan

DFA



SLR(1)

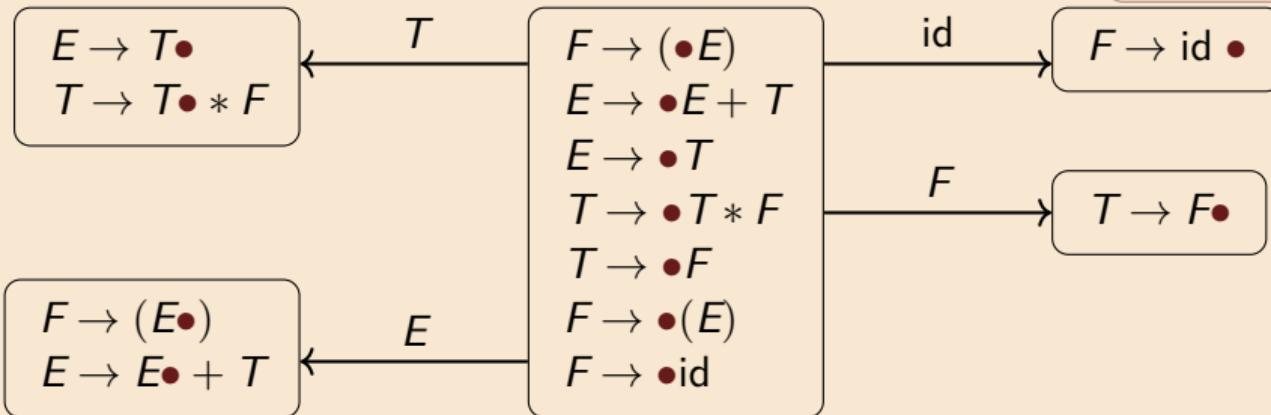
Parsing
with states

SLR(1)
limits

LR(1)

Grammar G'_2

$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + T \mid T \\ T &\rightarrow T * F \mid F \\ F &\rightarrow (E) \mid \text{id} \end{aligned}$$



Some DFA transitions for grammar G_2

Recap &
plan

DFA



SLR(1)

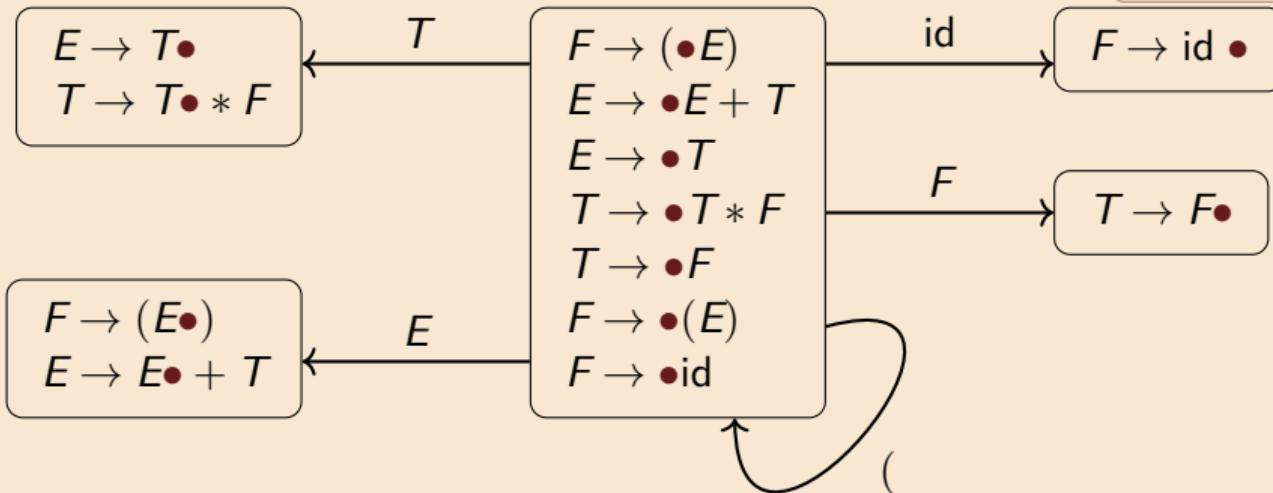
Parsing
with states

SLR(1)
limits

LR(1)

Grammar G'_2

$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + T \mid T \\ T &\rightarrow T * F \mid F \\ F &\rightarrow (E) \mid \text{id} \end{aligned}$$



Full DFA for the stack language of G_2

Recap & plan

DFA

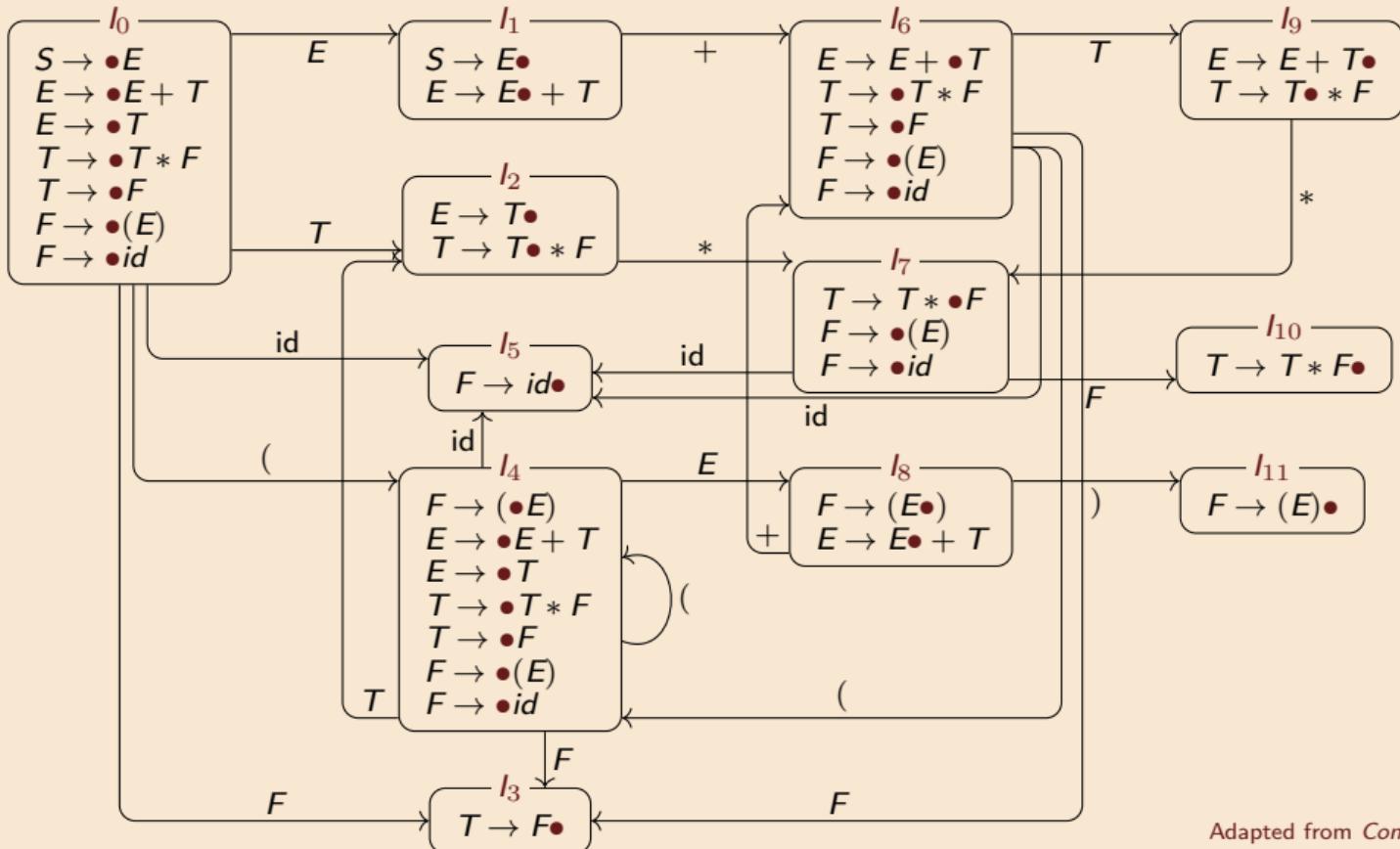


SLR(1)

Parsing with states

SLR(1) limits

LR(1)



Adapted from *Compilers*
(Aho, Lam, Sethi, Ullman)

SLR(1)

Resolving shift/reduce conflicts

Recap &
plan

DFA

SLR(1)

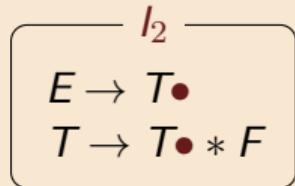
● ○ ○

Parsing
with states

SLR(1)
limits

LR(1)

The state I_2 has a **shift/reduce conflict**.



The **Simple LR(1)** approach resolves the conflict using the next token c :

shift

if $c = *$

reduce with $E \rightarrow T$

only if $c \in \text{FOLLOW}(E) = \{(, +, \$)\}$.

Deterministic SLR(1) parsing

Recap &
plan

DFA

SLR(1)



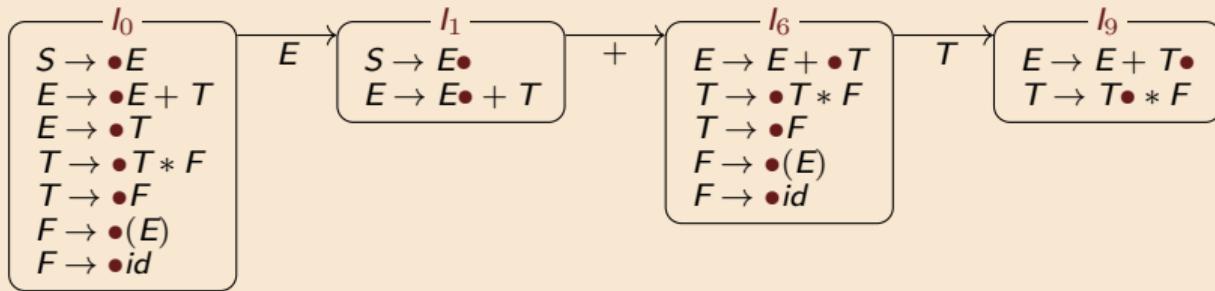
Parsing
with states

SLR(1)
limits

LR(1)

Recall: when the stack contains a , the parser is in state $\delta(I_0, a)$. For example,

$$\delta(I_0, E + T) = I_9$$



Let I be the current state and c the next token. Then:

1. When $A \rightarrow \beta \bullet c \gamma \in I$ then **shift** c onto stack
2. When $A \rightarrow \beta \bullet \in I$ and $c \in \text{FOLLOW}(A)$ then **reduce** with $A \rightarrow \beta$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift (

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

	stack,	input	state	action	reason
	\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
DFA	$\$(,$	$x + y)\$$	I_4	shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$($,	$x + y)\$$	I_4	shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$	I_5	reduce $F \rightarrow \text{id}$	"+" $\in \text{FOLLOW}(F)$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift $($	$F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$($,	$x + y)\$$	I_4	shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$	I_5	reduce $F \rightarrow \text{id}$	"+" $\in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$	I_3	reduce $T \rightarrow F$	"+" $\in \text{FOLLOW}(T)$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift $($	$F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$($,	$x + y)\$$	I_4	shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$	I_5	reduce $F \rightarrow \text{id}$	$"+" \in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$	I_3	reduce $T \rightarrow F$	$"+" \in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$	I_2	reduce $E \rightarrow T$	$"+" \in \text{FOLLOW}(E)$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$(,$	$x + y)\$$	I_4	shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$	I_5	reduce $F \rightarrow \text{id}$	"+" $\in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$	I_3	reduce $T \rightarrow F$	"+" $\in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$	I_2	reduce $E \rightarrow T$	"+" $\in \text{FOLLOW}(E)$
$\$(E,$	$+y)\$$	I_8	shift +	$E \rightarrow E\bullet + T \in \delta(I_0, (+)) = I_8$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift $($	$F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$($,	$x + y)\$$		shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$		reduce $F \rightarrow \text{id}$	$"+" \in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$		reduce $T \rightarrow F$	$"+" \in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$		reduce $E \rightarrow T$	$"+" \in \text{FOLLOW}(E)$
$\$(E,$	$+y)\$$		shift $+$	$E \rightarrow E\bullet + T \in \delta(I_0, (E)) = I_8$
$\$(E+,$	$y)\$$		shift y	$F \rightarrow \bullet\text{id} \in \delta(I_0, (E+)) = I_6$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift $($	$F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$($,	$x + y)\$$		shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$		reduce $F \rightarrow \text{id}$	$"+" \in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$		reduce $T \rightarrow F$	$"+" \in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$		reduce $E \rightarrow T$	$"+" \in \text{FOLLOW}(E)$
$\$(E,$	$+y)\$$		shift $+$	$E \rightarrow E\bullet + T \in \delta(I_0, (E) = I_8$
$\$(E+,$	$y)\$$		shift y	$F \rightarrow \bullet\text{id} \in \delta(I_0, (E+) = I_6$
$\$(E + y,$	$)\$$		reduce $F \rightarrow \text{id}$	$")" \in \text{FOLLOW}(F)$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift $($	$F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$($,	$x + y)\$$		shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$		reduce $F \rightarrow \text{id}$	$"+" \in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$		reduce $T \rightarrow F$	$"+" \in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$		reduce $E \rightarrow T$	$"+" \in \text{FOLLOW}(E)$
$\$(E,$	$+y)\$$		shift $+$	$E \rightarrow E\bullet + T \in \delta(I_0, (E) = I_8$
$\$(E+,$	$y)\$$		shift y	$F \rightarrow \bullet\text{id} \in \delta(I_0, (E+) = I_6$
$\$(E + y,$	$)\$$		reduce $F \rightarrow \text{id}$	$")" \in \text{FOLLOW}(F)$
$\$(E + F,$	$)\$$		reduce $T \rightarrow F$	$")" \in \text{FOLLOW}(T)$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$(,$	$x + y)\$$	I_4	shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$	I_5	reduce $F \rightarrow \text{id}$	$"+" \in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$	I_3	reduce $T \rightarrow F$	$"+" \in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$	I_2	reduce $E \rightarrow T$	$"+" \in \text{FOLLOW}(E)$
$\$(E,$	$+y)\$$	I_8	shift +	$E \rightarrow E\bullet + T \in \delta(I_0, (+) = I_8$
$\$(E+,$	$y)\$$	I_6	shift y	$F \rightarrow \bullet\text{id} \in \delta(I_0, (E+) = I_6$
$\$(E + y,$	$)\$$	I_5	reduce $F \rightarrow \text{id}$	$")" \in \text{FOLLOW}(F)$
$\$(E + F,$	$)\$$	I_3	reduce $T \rightarrow F$	$")" \in \text{FOLLOW}(T)$
$\$(E + T,$	$)\$$	I_9	reduce $E \rightarrow E + T$	$")" \in \text{FOLLOW}(E)$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$(,$	$x + y)\$$	I_4	shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$	I_5	reduce $F \rightarrow \text{id}$	$"+" \in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$	I_3	reduce $T \rightarrow F$	$"+" \in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$	I_2	reduce $E \rightarrow T$	$"+" \in \text{FOLLOW}(E)$
$\$(E,$	$+y)\$$	I_8	shift +	$E \rightarrow E\bullet + T \in \delta(I_0, (+) = I_8$
$\$(E+,$	$y)\$$	I_6	shift y	$F \rightarrow \bullet\text{id} \in \delta(I_0, (E+) = I_6$
$\$(E+y,$	$)\$$	I_5	reduce $F \rightarrow \text{id}$	$")" \in \text{FOLLOW}(F)$
$\$(E+F,$	$)\$$	I_3	reduce $T \rightarrow F$	$")" \in \text{FOLLOW}(T)$
$\$(E+T,$	$)\$$	I_9	reduce $E \rightarrow E + T$	$")" \in \text{FOLLOW}(E)$
$\$(E,$	$)\$$	I_8	shift)	$E \rightarrow (E\bullet) \in \delta(I_0, (E) = I_8$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$($,	$x + y)\$$		shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$		reduce $F \rightarrow \text{id}$	$"+" \in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$		reduce $T \rightarrow F$	$"+" \in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$		reduce $E \rightarrow T$	$"+" \in \text{FOLLOW}(E)$
$\$(E,$	$+y)\$$		shift +	$E \rightarrow E\bullet + T \in \delta(I_0, (E) = I_8$
$\$(E+,$	$y)\$$		shift y	$F \rightarrow \bullet\text{id} \in \delta(I_0, (E+) = I_6$
$\$(E + y,$)\$		reduce $F \rightarrow \text{id}$	$")" \in \text{FOLLOW}(F)$
$\$(E + F,$)\$		reduce $T \rightarrow F$	$")" \in \text{FOLLOW}(T)$
$\$(E + T,$)\$		reduce $E \rightarrow E + T$	$")" \in \text{FOLLOW}(E)$
$\$(E,$)\$		shift)	$E \rightarrow (E\bullet) \in \delta(I_0, (E) = I_8$
$\$(E),$	\$	I_{11}	reduce $F \rightarrow (E)$	$"\$" \in \text{FOLLOW}(F)$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$($,	$x + y)\$$		shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$		reduce $F \rightarrow \text{id}$	$"+" \in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$		reduce $T \rightarrow F$	$"+" \in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$		reduce $E \rightarrow T$	$"+" \in \text{FOLLOW}(E)$
$\$(E,$	$+y)\$$		shift +	$E \rightarrow E\bullet + T \in \delta(I_0, (E) = I_8$
$\$(E+,$	$y)\$$		shift y	$F \rightarrow \bullet\text{id} \in \delta(I_0, (E+) = I_6$
$\$(E+y,$)\$		reduce $F \rightarrow \text{id}$	$")" \in \text{FOLLOW}(F)$
$\$(E+F,$)\$		reduce $T \rightarrow F$	$")" \in \text{FOLLOW}(T)$
$\$(E+T,$)\$		reduce $E \rightarrow E + T$	$")" \in \text{FOLLOW}(E)$
$\$(E,$)\$		shift)	$E \rightarrow (E\bullet) \in \delta(I_0, (E) = I_8$
$\$(E),$	\$		reduce $F \rightarrow (E)$	$"\$" \in \text{FOLLOW}(F)$
$\$F,$	\$		reduce $T \rightarrow F$	$"\$" \in \text{FOLLOW}(T)$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

	stack,	input	state	action	reason
SLR(1)	\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
	$\$(,$	$x + y)\$$	I_4	shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
	$\$(x,$	$+y)\$$	I_5	reduce $F \rightarrow \text{id}$	$"+" \in \text{FOLLOW}(F)$
	$\$(F,$	$+y)\$$	I_3	reduce $T \rightarrow F$	$"+" \in \text{FOLLOW}(T)$
	$\$(T,$	$+y)\$$	I_2	reduce $E \rightarrow T$	$"+" \in \text{FOLLOW}(E)$
	$\$(E,$	$+y)\$$	I_8	shift +	$E \rightarrow E\bullet + T \in \delta(I_0, (E) = I_8$
	$\$(E+,$	$y)\$$	I_6	shift y	$F \rightarrow \bullet\text{id} \in \delta(I_0, (E+) = I_6$
	$\$(E+y,$)\$	I_5	reduce $F \rightarrow \text{id}$	$")" \in \text{FOLLOW}(F)$
	$\$(E+F,$)\$	I_3	reduce $T \rightarrow F$	$")" \in \text{FOLLOW}(T)$
	$\$(E+T,$)\$	I_9	reduce $E \rightarrow E + T$	$")" \in \text{FOLLOW}(E)$
	$\$(E,$)\$	I_8	shift)	$E \rightarrow (E\bullet) \in \delta(I_0, (E) = I_8$
	$\$(E),$	\$	I_{11}	reduce $F \rightarrow (E)$	$"\$" \in \text{FOLLOW}(F)$
	$\$F,$	\$	I_3	reduce $T \rightarrow F$	$"\$" \in \text{FOLLOW}(T)$
	$\$T,$	\$	I_2	reduce $E \rightarrow F$	$"\$" \in \text{FOLLOW}(E)$

Replay parsing of $(x + y)$ using SLR(1) actions

Recap &
plan

DFA

SLR(1)



Parsing
with states

SLR(1)
limits

LR(1)

stack,	input	state	action	reason
\$,	$(x + y)\$$	I_0	shift ($F \rightarrow \bullet(E) \in \delta(I_0, \epsilon) = I_0$
$\$(,$	$x + y)\$$	I_4	shift x	$F \rightarrow \bullet\text{id} \in \delta(I_0, ()) = I_4$
$\$(x,$	$+y)\$$	I_5	reduce $F \rightarrow \text{id}$	"+" $\in \text{FOLLOW}(F)$
$\$(F,$	$+y)\$$	I_3	reduce $T \rightarrow F$	"+" $\in \text{FOLLOW}(T)$
$\$(T,$	$+y)\$$	I_2	reduce $E \rightarrow T$	"+" $\in \text{FOLLOW}(E)$
$\$(E,$	$+y)\$$	I_8	shift +	$E \rightarrow E\bullet + T \in \delta(I_0, (E)) = I_8$
$\$(E+,$	$y)\$$	I_6	shift y	$F \rightarrow \bullet\text{id} \in \delta(I_0, (E+)) = I_6$
$\$(E+y,$)\$	I_5	reduce $F \rightarrow \text{id}$	")" $\in \text{FOLLOW}(F)$
$\$(E+F,$)\$	I_3	reduce $T \rightarrow F$	")" $\in \text{FOLLOW}(T)$
$\$(E+T,$)\$	I_9	reduce $E \rightarrow E + T$	")" $\in \text{FOLLOW}(E)$
$\$(E,$)\$	I_8	shift)	$E \rightarrow (E\bullet) \in \delta(I_0, (E)) = I_8$
$\$(E),$	\$	I_{11}	reduce $F \rightarrow (E)$	"\$" $\in \text{FOLLOW}(F)$
$\$F,$	\$	I_3	reduce $T \rightarrow F$	"\$" $\in \text{FOLLOW}(T)$
$\$T,$	\$	I_2	reduce $F \rightarrow E$	"\$" $\in \text{FOLLOW}(E)$
$\$E,$	\$	I_1	reduce $S \rightarrow E$	"\$" $\in \text{FOLLOW}(S)$

Parsing with states

Idea: don't restart the DFA at every step

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

Previous approach

Maintain a **stack of symbols**

$\$ (E + id$

At each step:

Use the **full stack**
to find items

New approach

Maintain a **stack of states**

0 4 1 6 5

At each step:

Use the **top of the stack**
to find actions

LR parsing with DFA states on the stack

Recap &
plan

DFA

SLR(1)

Parsing
with states
● ● ○ ○ ○

SLR(1)
limits

LR(1)

```
tok := NextToken()  
while true:  
    state := TopStackState()  
    if ACTION[state, tok] = SHIFT state  
        then push state  
        tok := NextToken()  
    else if ACTION[state, tok] = REDUCE  $A \rightarrow \beta$   
        then pop  $|\beta|$  states  
        push GOTO[TopStackState(), A]  
    else if ACTION[state, tok] = ACCEPT  
        then accept and exit  
    else ERROR
```

Constructing ACTION and GOTO for SLR(1)

Recap &
plan

If $A \rightarrow \alpha \bullet a \beta \in I_i$ and $\delta(I_i, a) = I_j$
then $\text{ACTION}[i, a] = \text{SHIFT } j$.

If $A \rightarrow \alpha \bullet \in I_i$ and $A \neq S$
then for each $a \in \text{FOLLOW}(A)$,
 $\text{ACTION}[i, a] = \text{REDUCE } A \rightarrow \alpha$

If $S \rightarrow \alpha \bullet \in I_i$
then $\text{ACTION}[i, \$] = \text{ACCEPT}$
If $\delta(I_i, A) = I_j$
then $\text{GOTO}[i, A] = j$

(ACTION resolves conflicts; GOTO records nonterminal transitions $I_i \xrightarrow{A} I_j$)

DFA
SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

ACTION and GOTO for G_2

Recap &
plan

DFA	STATE	ACTION					GOTO			
		id	+	*	()	\$	E	T	F
	0	s_5			s_4			1	2	3
	1		s_6				acc			
SLR(1)	2		r_2	s_7		r_2	r_2			
	3		r_4	r_4		r_4	r_4			
	4	s_5			s_4			8	2	3
	5		r_6	r_6		r_6	r_6			
	6	s_5			s_4			9	3	
	7	s_5			s_4					10
	8		s_6			s_{11}				
	9		r_1	s_7		r_1	r_1			
	10		r_3	r_3		r_3	r_3			
	11		r_5	r_5		r_5	r_5			

Parsing
with states
● ● ● ● ○

SLR(1)
limits

LR(1)

Adapted from *Compilers*
(Aho, Lam, Sethi, Ullman)

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION
0		id * id + id\$	shift

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION
0		id * id + id\$	shift
0 5	id	* id + id\$	reduce $F \rightarrow id$ GOTO[0, F] = 3

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	$GOTO[0, F] = 3$
0 3	F	* id + id\$	reduce $T \rightarrow F$	$GOTO[0, T] = 2$

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	T *	id + id\$	shift	

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	$T *$	id + id\$	shift	
0 2 7 5	$T * id$	+ id\$	reduce $F \rightarrow id$	GOTO[7, F] = 10

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	T *	id + id\$	shift	
0 2 7 5	T * id	+ id\$	reduce $F \rightarrow id$	GOTO[7, F] = 10
0 2 7 10	T * F	+ id\$	reduce $T \rightarrow T * F$	GOTO[0, T] = 2

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	T *	id + id\$	shift	
0 2 7 5	T * id	+ id\$	reduce $F \rightarrow id$	GOTO[7, F] = 10
0 2 7 10	T * F	+ id\$	reduce $T \rightarrow T * F$	GOTO[0, T] = 2
0 2	T	+ id\$	reduce $E \rightarrow T$	GOTO[0, E] = 1

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	T *	id + id\$	shift	
0 2 7 5	T * id	+ id\$	reduce $F \rightarrow id$	GOTO[7, F] = 10
0 2 7 10	T * F	+ id\$	reduce $T \rightarrow T * F$	GOTO[0, T] = 2
0 2	T	+ id\$	reduce $E \rightarrow T$	GOTO[0, E] = 1
0 1	E	+ id\$	shift	

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	T *	id + id\$	shift	
0 2 7 5	T * id	+ id\$	reduce $F \rightarrow id$	GOTO[7, F] = 10
0 2 7 10	T * F	+ id\$	reduce $T \rightarrow T * F$	GOTO[0, T] = 2
0 2	T	+ id\$	reduce $E \rightarrow T$	GOTO[0, E] = 1
0 1	E	+ id\$	shift	
0 1 6	E +	id\$	shift	

Adapted from *Compilers*
(Aho, Lam, Sethi, Ullman)

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	T *	id + id\$	shift	
0 2 7 5	T * id	+ id\$	reduce $F \rightarrow id$	GOTO[7, F] = 10
0 2 7 10	T * F	+ id\$	reduce $T \rightarrow T * F$	GOTO[0, T] = 2
0 2	T	+ id\$	reduce $E \rightarrow T$	GOTO[0, E] = 1
0 1	E	+ id\$	shift	
0 1 6	E +	id\$	shift	
0 1 6 5	E + id	\$	reduce $F \rightarrow id$	GOTO[6, F] = 3

Adapted from *Compilers*
(Aho, Lam, Sethi, Ullman)

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	T *	id + id\$	shift	
0 2 7 5	T * id	+ id\$	reduce $F \rightarrow id$	GOTO[7, F] = 10
0 2 7 10	T * F	+ id\$	reduce $T \rightarrow T * F$	GOTO[0, T] = 2
0 2	T	+ id\$	reduce $E \rightarrow T$	GOTO[0, E] = 1
0 1	E	+ id\$	shift	
0 1 6	E +	id\$	shift	
0 1 6 5	E + id	\$	reduce $F \rightarrow id$	GOTO[6, F] = 3
0 1 6 3	E + F	\$	reduce $T \rightarrow F$	GOTO[6, T] = 9

Adapted from *Compilers*
(Aho, Lam, Sethi, Ullman)

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	T *	id + id\$	shift	
0 2 7 5	T * id	+ id\$	reduce $F \rightarrow id$	GOTO[7, F] = 10
0 2 7 10	T * F	+ id\$	reduce $T \rightarrow T * F$	GOTO[0, T] = 2
0 2	T	+ id\$	reduce $E \rightarrow T$	GOTO[0, E] = 1
0 1	E	+ id\$	shift	
0 1 6	E +	id\$	shift	
0 1 6 5	E + id	\$	reduce $F \rightarrow id$	GOTO[6, F] = 3
0 1 6 3	E + F	\$	reduce $T \rightarrow F$	GOTO[6, T] = 9
0 1 6 9	E + T	\$	reduce $E \rightarrow E + T$	GOTO[0, E] = 1

Adapted from *Compilers*
(Aho, Lam, Sethi, Ullman)

Example parse

Recap &
plan

DFA

SLR(1)

Parsing
with states



SLR(1)
limits

LR(1)

STACK	SYMBOLS	INPUT	ACTION	
0		id * id + id\$	shift	
0 5	id	* id + id\$	reduce $F \rightarrow id$	GOTO[0, F] = 3
0 3	F	* id + id\$	reduce $T \rightarrow F$	GOTO[0, T] = 2
0 2	T	* id + id\$	shift	
0 2 7	T *	id + id\$	shift	
0 2 7 5	T * id	+ id\$	reduce $F \rightarrow id$	GOTO[7, F] = 10
0 2 7 10	T * F	+ id\$	reduce $T \rightarrow T * F$	GOTO[0, T] = 2
0 2	T	+ id\$	reduce $E \rightarrow T$	GOTO[0, E] = 1
0 1	E	+ id\$	shift	
0 1 6	E +	id\$	shift	
0 1 6 5	E + id	\$	reduce $F \rightarrow id$	GOTO[6, F] = 3
0 1 6 3	E + F	\$	reduce $T \rightarrow F$	GOTO[6, T] = 9
0 1 6 9	E + T	\$	reduce $E \rightarrow E + T$	GOTO[0, E] = 1
0 1	E	\$	accept	

Adapted from *Compilers*
(Aho, Lam, Sethi, Ullman)

The limits of SLR(1)

The limits of SLR(1)

Recap &
plan

DFA

SLR(1)

Parsing
with states

SLR(1)
limits
● ○ ○

LR(1)

A new example grammar (for *assignment expressions*):

$$G_4 = \langle N_4, T_4, P_4, S' \rangle$$

$$N_4 = \{S', S, L, R\}$$

$$T_4 = \{*, :=, id\}$$

$$\begin{aligned}P_4 : \quad & S' \rightarrow S \$ \\& S \rightarrow L := R \mid R \\& L \rightarrow *R \mid id \\& R \rightarrow L\end{aligned}$$

LR(0) DFA for grammar G_4

Recap &
plan

DFA

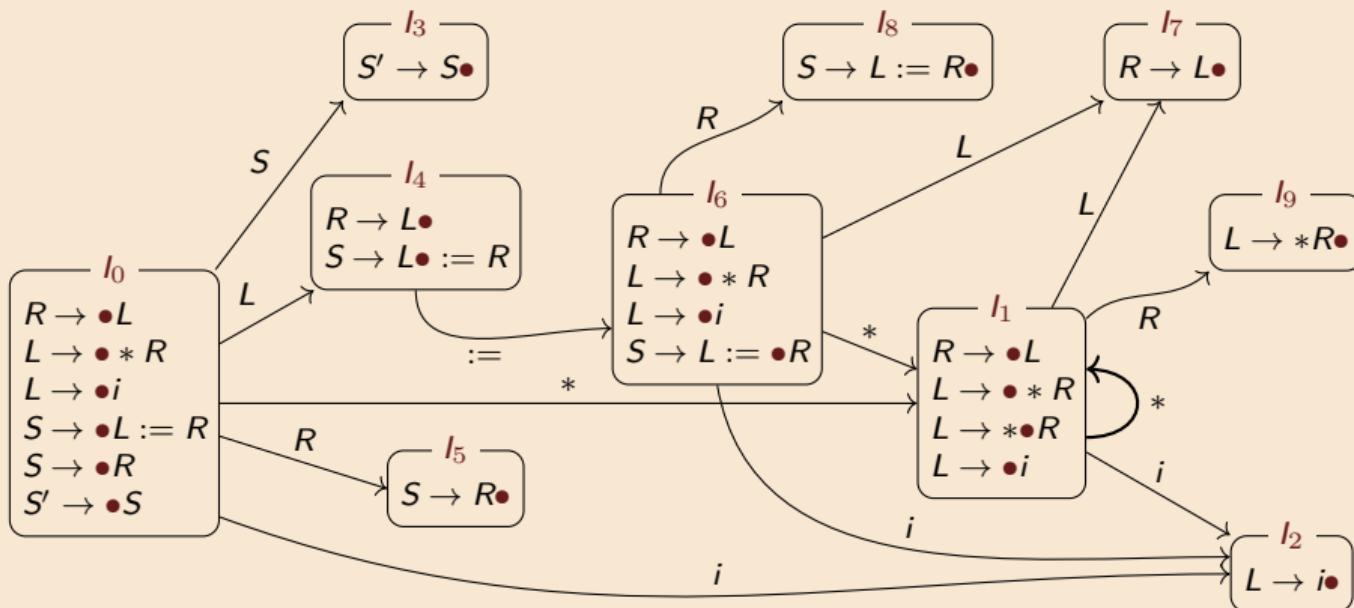
SLR(1)

Parsing
with states

SLR(1)
limits

- ● ○

LR(1)



LR(0) DFA for grammar G_4

Recap &
plan

DFA

SLR(1)

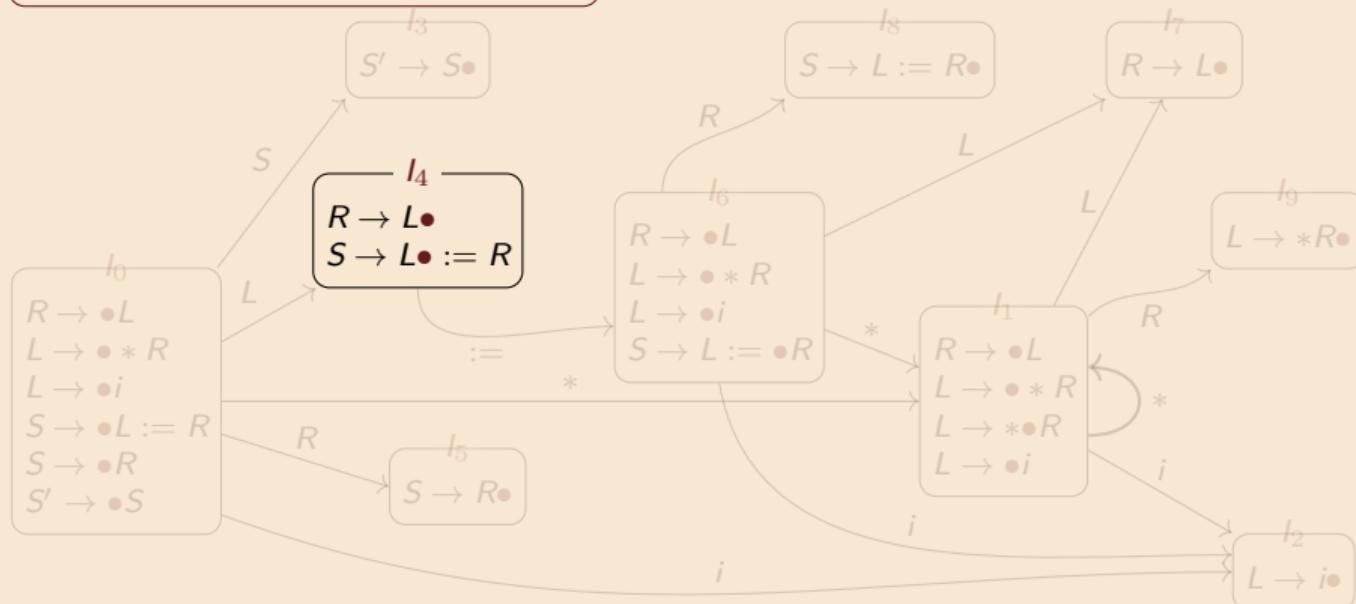
Parsing
with states

SLR(1)
limits
● ● ○

LR(1)

Ambiguity

In state 4 there is a shift/reduce conflict
between $S \rightarrow L\bullet := R$ and $R \rightarrow L\bullet$



SLR(1) cannot resolve this conflict.

Recap &
plan

DFA

SLR(1)

Parsing
with states

SLR(1)
limits



LR(1)

Suppose we see $:=$ in the input in state I_4 . Then:

shifting is valid

Since $S \rightarrow L \bullet := R \in I_4$,

and $\delta(I_4, ":=") = I_6$,

$\text{ACTION}[4, ":="] = \text{shift } 6$

reducing is valid

Since $R \rightarrow L \bullet \in I_4$

and $"":=\in \text{FOLLOW}(R)$,

$\text{ACTION}[4, ":="] = \text{reduce } R \rightarrow L$

LR(1)

Recap &
plan

DFA

SLR(1)

Parsing
with states

SLR(1)
limits

LR(1)

With SLR(1) there may be

shift-reduce

conflicts

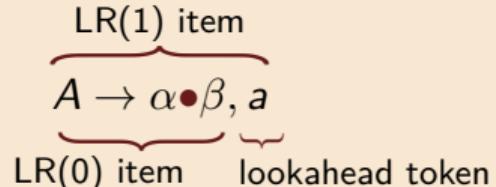
reduce-reduce

conflicts

when ACTION and GOTO are not uniquely defined.

Options: fix the grammar, or use a more powerful parsing technique.

LR(1) parsing extends LR(0) items with an explicit lookahead token a :



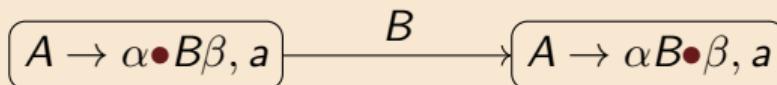
Define an NFA with LR(1) items as states

Recap &
plan

DFA

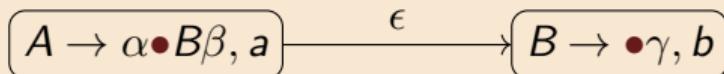


SLR(1)



Parsing
with states

For each $b \in \text{FIRST}(\beta a)$:



LR(1)



LR(1) DFA for grammar G_4

Recap &
plan

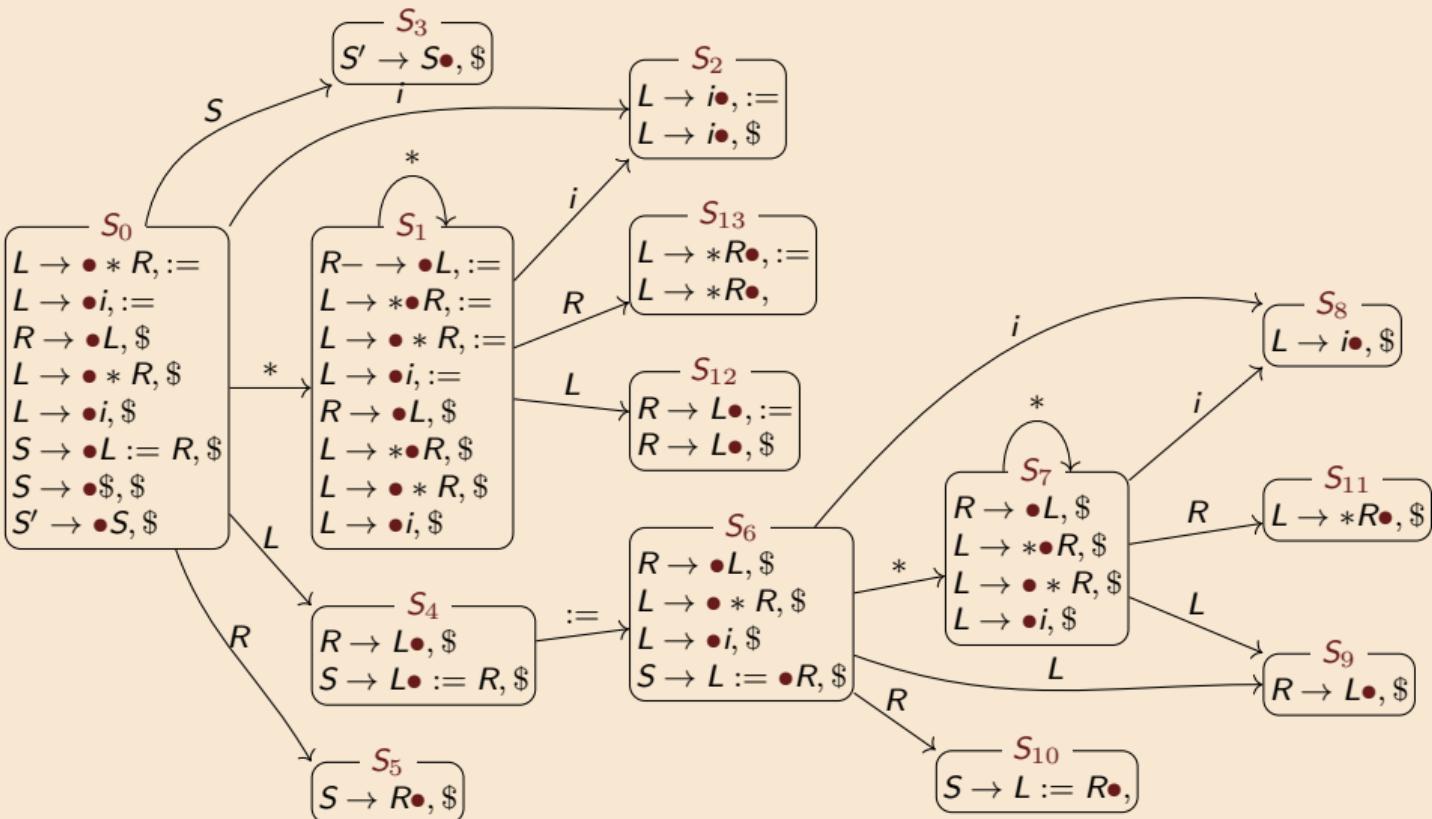
DFA

SLR(1)

Parsing
with states

SLR(1)
limits

LR(1)



LR(1) DFA for grammar G_4

Recap &
plan

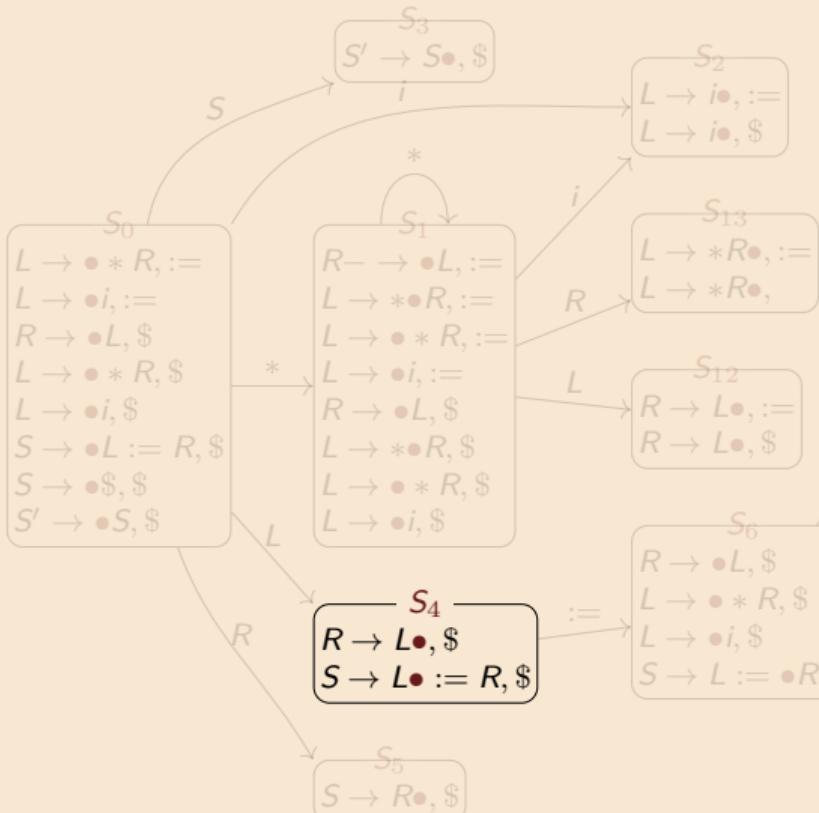
DFA

SLR(1)

Parsing
with states

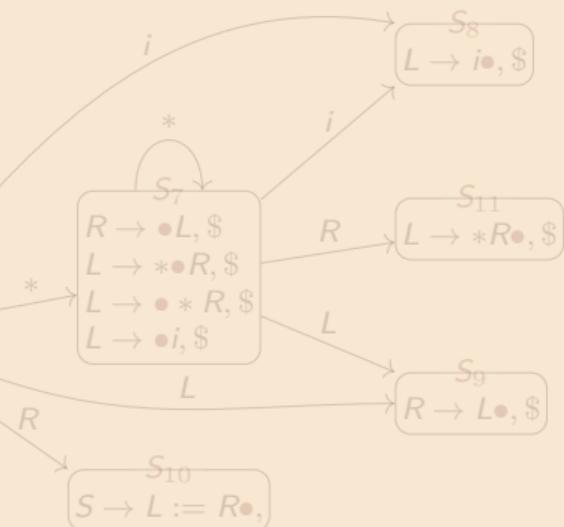
SLR(1)
limits

LR(1)



No ambiguity.

Reduce $R \rightarrow L$ only if next token is $\$$.
Shift only if next token is $:=$.



Constructing ACTION and GOTO for LR(1)

Recap &
plan

DFA

SLR(1)

Parsing
with states

SLR(1)
limits

If $[A \rightarrow \alpha \bullet a\beta, b] \in I_i$ and $\delta(I_i, a) = I_j$

then ACTION[i, a] = SHIFT j.

If $[A \rightarrow \alpha \bullet, b] \in I_i$ and $A \neq S$,

then ACTION[i, b] = REDUCE $A \rightarrow \alpha$

If $[S \rightarrow \alpha \bullet, \$] \in I_i$

then ACTION[i, \\$] = ACCEPT

If $\delta(I_i, A) = I_j$

then GOTO[i, A] = j.

Key change from SLR(1): use lookahead (i.e. FIRST), not FOLLOW, to select REDUCE actions

LR(1)



Recap & plan

DFA

SLR(1)

Parsing with states

SLR(1) limits

LR(1)



SLR(1)

If $[A \rightarrow \alpha \bullet] \in I_i$ and $A \neq S$
then for each $a \in \text{FOLLOW}(A)$,
 $\text{ACTION}[i, a] = \text{reduce } A \rightarrow \alpha$

LR(1)

If $[A \rightarrow \alpha \bullet, b] \in I_i$ and $A \neq S$
then
 $\text{ACTION}[i, b] = \text{reduce } A \rightarrow \alpha$

NB: b used *only* for reductions, not for shifts

LR(1) more powerful than SLR(1)

LR(1) DFA may have a very large number of states.

LALR¹ optimises DFA, collapsing states (but can give strange error messages)

¹Implemented in yacc; not covered here

Next time: translation