

Overview of Natural Language Processing

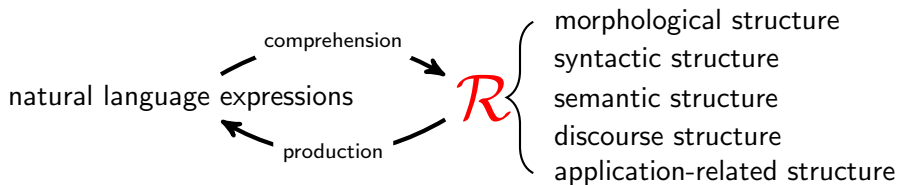
Part II & ACS L390

Lecture 7: Grammar Induction

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How can we get proper $\mathcal{R}$?

Learning from incomplete data

- Observed data $D = \{x^{(1)}, x^{(2)}, \dots, x^{(u)}\}$ ▷ e.g. word sequences
- Hidden structure $\mathcal{H}$ ▷ e.g. POS tag sequences
- $p(D; \theta) = \sum_{\mathcal{H}} p(D, \mathcal{H}; \theta)$
- **Goal:** find θ to maximize $p(D; \theta)$

Expectation Maximisation

EM in general

Challenge

$$\log p(D; \theta) = \log \sum_{\mathcal{H}} p(D, \mathcal{H}; \theta)$$

How

- An EM iteration starts from $\theta^{(t)}$
- The E-step:

$$q(\mathcal{H}) = p(\mathcal{H}|D; \theta^{(t)})$$

- The M-step:

$$\theta^{(t+1)} = \arg \max_{\theta} \sum_{\mathcal{H}} q(\mathcal{H}) \log \frac{p(D, \mathcal{H}; \theta)}{q(\mathcal{H})}$$

EM in general

Challenge

$$\log p(D; \theta) = \log \sum_{\mathcal{H}} p(D, \mathcal{H}; \theta)$$

How

- An EM iteration starts from $\theta^{(t)}$
- The E-step: (E=Expectation)

$$q(\mathcal{H}) = p(\mathcal{H}|D; \theta^{(t)})$$

- The M-step: (M=Maximization)

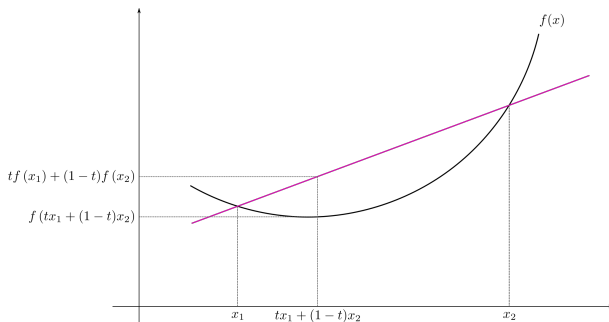
$$\theta^{(t+1)} = \arg \max_{\theta} \sum_{\mathcal{H}} q(\mathcal{H}) \log \frac{p(D, \mathcal{H}; \theta)}{q(\mathcal{H})}$$

Soundness (1)

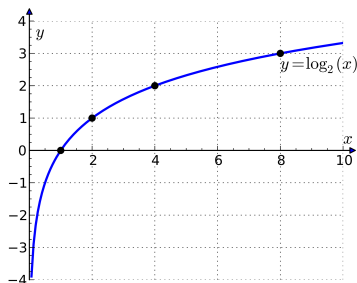
Jensen's inequality

Let f be a convex function, and let X be a random variable. Then:

$$E[f(X)] \geq f(E[X])$$



Soundness (2)



$$\begin{aligned} L(\theta) &= \sum_i \log p(x^{(i)}; \theta) \\ &= \sum_i \log \sum_y p(x^{(i)}, y; \theta) \\ &= \sum_i \log \sum_y q_i(y) \frac{p(x^{(i)}, y; \theta)}{q_i(y)} \\ &\geq \sum_i \sum_y q_i(y) \log \frac{p(x^{(i)}, y; \theta)}{q_i(y)} \end{aligned}$$

Key idea

- $\sum_i \sum_y q_i(y) \log \frac{p(x^{(i)}, y; \theta)}{q_i(y)}$ is a **lower bound** of $L(\theta)$.
- If this bound is tight, we can instead maximize it.

Soundness (3)

Key idea

$\sum_i \sum_y q_i(y) \log \frac{p(x^{(i)}, y; \theta)}{q_i(y)}$ is a lower bound of $L(\theta)$.

Make the bound tight for a particular value of θ

$$\log \sum_y q_i(y) \frac{p(x^{(i)}, y; \theta)}{q_i(y)} \stackrel{?}{=} \sum_y q_i(y) \log \frac{p(x^{(i)}, y; \theta)}{q_i(y)}$$

Posterior Distribution

$$\begin{aligned} q_i(y) &\propto p(x^{(i)}, y; \theta) \\ q_i(y) &= \frac{p(x^{(i)}, y; \theta)}{\sum_y p(x^{(i)}, y; \theta)} \\ &= p(y|x^{(i)}; \theta) \end{aligned}$$

Soundness (4)

The EM algorithm

E-step:

$$q_i(y) = p(y|x^{(i)}; \theta^{(t)})$$

M-step:

$$\theta^{(t+1)} = \arg \max_{\theta} \sum_i \sum_y q_i(y) \log \frac{p(x^{(i)}, y; \theta)}{q_i(y)}$$

Soundness (5)

$$L_b(\theta^{(t)}) = \sum_i \sum_y q_i^{(t)}(y) \log \frac{p(x^{(i)}, y; \theta^{(t)})}{q_i^{(t)}(y)}$$

Convergence

$$\begin{aligned} L_b(\theta^{(t+1)}) &\geq \sum_i \sum_y q_i^{(\textcolor{red}{t})}(y) \log \frac{p(x^{(i)}, y; \theta^{(\textcolor{blue}{t}+1)})}{q_i^{(\textcolor{red}{t})}(y)} \\ &\geq \sum_i \sum_y q_i^{(t)}(y) \log \frac{p(x^{(i)}, y; \theta^{(\textcolor{blue}{t})})}{q_i^{(t)}(y)} \\ &= L_b(\theta^{(t)}) \end{aligned}$$

Hidden Markov Model and EM

Probabilistic models for sequence pairs

- We have two sequences of random variables: $X_1, X_2, \dots, X_n$ and $S_1, S_2, \dots, S_n$
- Intuitively, each X_i corresponds to an **observation** and each S_i corresponds to an underlying **state** that generated the observation. Assume that each S_i is in $\{1, 2, \dots, k\}$, and each X_i is in $\{1, 2, \dots, o\}$.
- How do we model the joint distribution

$$P(X_1 = x_1, \dots, X_n = x_n, S_1 = s_1, \dots, S_n = s_n)$$

Hidden Markov Models

An HMM takes the following form

$$p(x_1 \dots x_n, s_1 \dots s_n; \theta) = t(s_1) \prod_{j=2}^n t(s_j | s_{j-1}) \prod_{j=1}^n e(x_j | s_j)$$

Parameters in the model

- ❶ Initial state parameters ϕ_s for $s \in \{1, 2, \dots, k\}$
- ❷ Transition parameters $\phi_{s'|s}$ for $s, s' \in \{1, 2, \dots, k\}$
- ❸ Emission parameters $\phi_{e|s}$ for $s \in \{1, 2, \dots, k\}$ and $e \in \{1, 2, \dots, o\}$

If we use a specific symbol to denote *stop of a sequence*: $s_0 = *$

- Initial state parameters $\phi_{s|*}$
- Just look like transition parameters

Parameter estimation with fully observed data

- $\text{count}(i, s \rightarrow s')$: the number of times state s' follows state s in the i 'th training example.

$$\text{count}(i, s \rightarrow s') = \sum_{j=1}^{|s^{(i)}|-1} \mathbb{1}_{\{s_j^{(i)}=s \wedge s_{j+1}^{(i)}=s'\}}$$

- $\text{count}(i, s \rightarrow e)$: the number of times state s is paired with emission x in the i 'th training example.

$$\text{count}(i, s \rightarrow e) = \sum_{j=1}^{|s^{(i)}|} \mathbb{1}_{\{s_j^{(i)}=s \wedge e_j^{(i)}=e\}}$$

- $\text{count}(i, s)$: to be 1 if state s is the initial state, and 0 otherwise.

$$\text{count}(i, s) = \mathbb{1}_{\{s_1^{(i)}=s\}}$$

$\mathbb{1}_A$ is an indicator function: $\mathbb{1}_A(x) = 1$ if $x \in A$, and $\mathbb{1}_A(x) = 0$ otherwise.

Maximum-likelihood estimation

- ① Transition probabilities:

$$\phi_{s'|s} = \frac{\sum_{i=1}^m \underline{\text{count}}(i, s \rightarrow s')}{\sum_{i=1}^m \sum_{s'} \underline{\text{count}}(i, s \rightarrow s')}$$

- ② Emission probabilities:

$$\phi_{e|s} = \frac{\sum_{i=1}^m \underline{\text{count}}(i, s \rightarrow e)}{\sum_{i=1}^m \sum_e \underline{\text{count}}(i, s \rightarrow e)}$$

- ③ Initial state probabilities:

$$\phi_s = \frac{\sum_{i=1}^m \underline{\text{count}}(i, s)}{m}$$

The Viterbi algorithm (1)

Task 1: get the most likely state sequence for x is

$$\arg \max_{s_1, \dots, s_n} p(x_1 \dots x_n, s_1 \dots s_n; \theta)$$

Define a dynamic programming table

$$\pi_t(s) = \text{maximum probability of a tag sequence ending in tag } s \text{ at position } t$$

that is,

$$\pi_t(s) = \max_{s_1, \dots, s_{t-1}} \left(\prod_{j=1}^{t-1} \phi_{s_j | s_{j-1}} \phi_{x_j | s_j} \right) \times \phi_{s_t | s_{t-1}} \times \phi_{x_t | s_t}$$

The Viterbi algorithm (2)

$$\pi_t(s) = \max_{s_1, \dots, s_{t-1}} \left(\prod_{j=1}^{t-1} \phi_{s_j | s_{j-1}} \phi_{x_j | s_j} \right) \times \phi_{s_t | s_{t-1}} \times \phi_{x_t | s_t}$$

Recursive definition

- Base case:

$$\pi_1(s) = \phi_{x_1 | s} \times \phi_{s | *}$$

- For any $t \in \{2, \dots, n\}$, for any $s \in \{1, \dots, k\}$:

$$\pi_t(s) = \max_{s' \in \{1, \dots, k\}} (\pi_{t-1}(s') \times \phi_{s | s'} \times \phi_{x_t | s})$$

The Viterbi algorithm (3)

- **Input:** a sentence $x_1, \dots, x_n$, parameters $\phi_{s'|s}$ and $\phi_{e|s}$
- **Initialization:** Set $\pi_0^* = 1$, and $\pi_0(s) = 0$ for all $s \in \{1, \dots, k\}$

- **Algorithm:**

- For $t = 1, \dots, n$,
 - For $s \in \{1, \dots, k\}$,

$$\pi_t(s) = \max_{s' \in \{1, \dots, k\}} (\pi_{t-1}(s') \times \phi_{s|s'} \times \phi_{x_t|s})$$

$$bp_t(s) = \arg \max_{s' \in \{1, \dots, k\}} (\pi_{t-1}(s') \times \phi_{s|s'} \times \phi_{x_t|s})$$

- Set

$$s_n = \arg \max_{s' \in \{1, \dots, k\}} (\pi_n(s') \times \phi_{s'|s} \times \phi_{*|s})$$

- For $t = (n - 1), \dots, 1$,

$$s_t = bp_{t+1}(s_{t+1})$$

- **Return** the tag sequence $s_1, \dots, s_n$.

The forward algorithm (1)

Task 2: for a given input sequence $x_1, \dots, x_n$, find

$$p(x_1 \dots x_n; \theta) = \sum_{s_1, \dots, s_n} p(x_1 \dots x_n, s_1 \dots s_n; \theta)$$

Define a dynamic programming table

$\alpha_t(s)$ = sum of probabilities of all tag sequences ending in tag s at position t

that is,

$$\alpha_t(s) = \sum_{s_1, \dots, s_{t-1}} \left(\prod_{j=1}^{t-1} \phi_{s_j | s_{j-1}} \phi_{x_j | s_j} \right) \times \phi_{s_t | s_{t-1}} \times \phi_{x_t | s_t}$$

The forward algorithm (2)

$$\alpha_t(s) = \sum_{s_1, \dots, s_{t-1}} \left(\prod_{j=1}^{t-1} \phi_{s_j | s_{j-1}} \phi_{x_j | s_j} \right) \times \phi_{s_t | s_{t-1}} \times \phi_{x_t | s_t}$$

Recursive definition

- For $s \in \mathcal{S}$,

$$\alpha_1(s) = \phi_{x_1 | s} \times \phi_{s | *}$$

- For any $t \in \{2, \dots, n\}$, for any $s \in \mathcal{S}$:

$$\alpha_t(s) = \sum_{s' \in \mathcal{S}} \alpha_{t-1}(s') \times \phi_{s | s'} \times \phi_{x_t | s}$$

The forward algorithm (3)

- **Input:** a sentence $x_1, \dots, x_n$, parameters $\phi_{s'|s}$ and $\phi_{e|s}$
- **Initialization:** Set $\alpha_0^* = 1$, and $\alpha_0(s) = 0$ for all $s \in \{1, \dots, k\}$
- **Algorithm:**
 - For $t = 1, \dots, n$,
 - For $s \in \{1, \dots, k\}$,

$$\alpha_t(s) = \sum_{s' \in \{1, \dots, k\}} (\alpha_{t-1}(s') \times \phi_{s|s'} \times \phi_{x_t|s})$$

- **Return:**

$$\sum_{s \in \{1, \dots, k\}} \alpha_n(s)$$

Generalization: Semirings (1)

The Viterbi algorithm and the forward algorithm are almost the same.

Viterbi and Forward algorithms correspond to exactly the same calculation, except one maximizes and the other sums.

Only some mathematical **properties** about operations are relevant $\Rightarrow$
Thinking about **abstract algebra**

The same abstract algorithm instantiated in two different **semirings**.

Semirings

A semiring is a set $\mathcal{A}$ equipped with two binary operations $\oplus$ and $\otimes$, such that:

- $\oplus$ is associative and commutative
 - $(a \oplus b) \oplus c = a \oplus (b \oplus c)$
 - $a \oplus b = b \oplus a$
- $\otimes$ is associative and distributes over $\oplus$
 - $(a \otimes b) \otimes c = a \otimes (b \otimes c)$
 - $a \otimes (b \oplus c) = (a \otimes b) \oplus (a \otimes c)$
 - $(a \oplus b) \otimes c = (a \otimes c) \oplus (b \otimes c)$
- Identity elements
 - $a \oplus \mathbf{0} = a$
 - $a \otimes \mathbf{1} = a$
 - $a \otimes \mathbf{0} = \mathbf{0} \otimes a = \mathbf{0}$

	Forward	Viterbi
$\mathcal{A}$	$\mathbb{R}_{\geq 0}$	$\mathbb{R}_{\geq 0}$
$\oplus$	$a + b$	$\max(a, b)$
$\otimes$	$a \times b$	$a \times b$
$\mathbf{0}$	0	0
$\mathbf{1}$	1	1

Generalization: Semirings (2)

Generalization

To calculate:

$$\bigoplus_{s \in \mathcal{S}^n} \left(\bigotimes_{t=2}^n \phi(s_t, s_{t-1}) \right)$$

A dynamic programming solution:

$$\gamma_t(s) = \bigoplus_{s' \in \mathcal{S}} (\gamma_{t-1}(s') \otimes \phi(s_t = s, s_{t-1} = s'))$$

Generalization: Semirings (3)

If

$$\gamma_t(s) = \bigoplus_{s_1 \dots s_{t-1} \in \mathcal{S}, S_t = s} \left(\bigotimes_{j=2}^t \phi(s_j, s_{j-1}) \right)$$

then,

$$\begin{aligned} \gamma_{t+1}(s) &= \bigoplus_{s' \in \mathcal{S}} \left(\gamma_t(s') \otimes \phi(S_{t+1} = s, S_t = s') \right) \\ &= \bigoplus_{s' \in \mathcal{S}} \left\{ \left[\bigoplus_{s_1 \dots s_{t-1} \in \mathcal{S}, S_t = s'} \left(\bigotimes_{j=2}^t \phi(s_j, s_{j-1}) \right) \right] \otimes \phi(s, s') \right\} \\ &= \bigoplus_{s' \in \mathcal{S}} \left\{ \bigoplus_{s_1 \dots s_{t-1} \in \mathcal{S}, S_t = s'} \left[\left(\bigotimes_{j=2}^t \phi(s_j, s_{j-1}) \right) \otimes \phi(s, s') \right] \right\} \end{aligned}$$

Generalization: Semirings (4)

$$\begin{aligned}
 \gamma_{t+1}(s) &= \bigoplus_{s' \in \mathcal{S}} \left\{ \bigoplus_{s_1 \dots s_{t-1} \in \mathcal{S}, S_t = s'} \left[\left(\bigotimes_{j=2}^t \phi(s_j, s_{j-1}) \right) \otimes \phi(s, s') \right] \right\} \\
 &= \bigoplus_{s' \in \mathcal{S}} \left(\bigoplus_{s_1 \dots s_{t-1} \in \mathcal{S}, S_t = s', S_{t+1} = s} \left(\bigotimes_{j=2}^{t+1} \phi(s_j, s_{j-1}) \right) \right) \\
 &= \bigoplus_{s_1 \dots s_t \in \mathcal{S}, S_{t+1} = s} \left(\bigotimes_{j=2}^{t+1} \phi(s_j, s_{j-1}) \right)
 \end{aligned}$$

By induction, we can prove,

$$\bigoplus_{s \in \mathcal{S}^n} \left(\bigotimes_{t=2}^n \phi(s_t, s_{t-1}) \right) = \bigoplus_{s \in \mathcal{S}} \gamma_n(s)$$

Probability of each state/transition

- Transition probabilities:

$$\phi_{s'|s} = \frac{\sum_{i=1}^m \underline{\text{count}}(i, s \rightarrow s')}{\sum_{i=1}^m \sum_{s'} \underline{\text{count}}(i, s \rightarrow s')}$$

- Emission probabilities:

$$\phi_{e|s} = \frac{\sum_{i=1}^m \underline{\text{count}}(i, s \rightarrow e)}{\sum_{i=1}^m \sum_e \underline{\text{count}}(i, s \rightarrow e)}$$

Probability of each state/transition

- Transition probabilities:

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- Emission probabilities:

$$\phi_{e|s} = \frac{\sum_{i=1}^m \underline{\text{count}}(i, s \rightarrow e)}{\sum_{i=1}^m \sum_e \underline{\text{count}}(i, s \rightarrow e)}$$

- For $j = \{1, \dots, n\}$ and $s = \mathcal{S}$, find

$$p(x_1 \dots x_n, \textcolor{red}{S}_j = \textcolor{red}{s}; \theta) = \sum_{s_j = s} p(x_1, \dots, x_n, s_1, \dots, s_n; \theta)$$

- For $j = \{1, \dots, n-1\}$ and $s, s' = \mathcal{S}$, find

$$p(x_1 \dots, \textcolor{red}{S}_j = \textcolor{red}{s}, \textcolor{red}{S}_{j+1} = \textcolor{red}{s}'; \theta) = \sum_{s_j = s, s_{j+1} = s'} p(x_1, \dots, x_n, s_1, \dots, s_n; \theta)$$

The forward-backward algorithm (1)

- ...: Something independent with $S_j, S_{j+1}, \dots$
- ...: Something independent with $\dots, S_{j-1}, S_j$.
- Consider: $aA + aB + bA + bB = (a + b)(A + B)$

Decompostion

$$\begin{aligned} & \sum_{S_j=s} \dots p(S_j = s | s_{j-1}) p(x_j | S_j = s) p(s_{j+1} | S_j = s) p(x_{j+1} | s_{j+1}) \dots \\ &= \underbrace{\sum_{S_j=s} \dots p(S_j = s | s_{j-1}) p(x_j | S_j = s)}_{\text{forward}} \underbrace{\sum_{S_j=s} p(s_{j+1} | S_j = s) p(x_{j+1} | s_{j+1}) \dots}_{\text{backward}} \end{aligned}$$

Forward and backward probabilities

Forward probabilities $\alpha_t(s)$

Sum of probabilities of all tag sequences ending in tag s at position t :

$$\alpha_t(s) = \sum_{s_0=*, s_1 \dots s_{t-1}} \left[\left(\prod_{j=1}^{t-1} \phi_{s_j | s_{j-1}} \phi_{x_j | j s_j} \right) \phi_{s | s_{t-1}} \phi_{x_t | s} \right]$$

Backward probabilities $\beta_t(s)$

Sum of probabilities of all tag sequences starting with state s at position j and going to the end of the sequence:

$$\beta_t(s) = \sum_{s_{t+1} \dots s_n} \left[\phi_{x_{t+1} | s_{t+1}} \phi_{s_{t+1} | s} \left(\prod_{j=t+2}^n \phi_{s_j | s_{j-1}} \phi_{x_j | j s_j} \right) \right]$$

Recursive definitions of the backward probabilities

Recursive definition

- For $s \in \mathcal{S}$,

$$\beta_n(s) = 1$$

- For any $t \in \{n-1, \dots, 1\}$, for any $s \in \mathcal{S}$:

$$\beta_t(s) = \sum_{s' \in \mathcal{S}} \beta_{t+1}(s') \times \phi_{s'|s} \times \phi_{x_{t+1}|s'}$$

The forward-backward algorithm (2)

$$\begin{aligned} p(x_1 \dots x_n, S_j = s) &= \sum_{S_j = s} \left(\prod_{i=1}^n p(s_i | s_{i-1}) p(x_i | s_i) \right) \\ &= \sum_{S_j = s} \left(\prod_{i=1}^{j-1} p(s_i | s_{i-1}) p(x_i | s_i) \right) \times p(s_j | s_{j-1}) p(x_j | s_j) \\ &\quad \times p(s_{j+1} | s_j) p(x_{j+1} | s_{j+1}) \times \left(\prod_{i=j+2}^n p(s_i | s_{i-1}) p(x_i | s_i) \right) \\ &= \alpha_j(s) \times \beta_j(s) \end{aligned}$$

Consider: $aA + aB + bA + bB = (a + b)(A + B)$

Per-word posterior decoding

- Once you have all forward/backward probabilities, you can calculate the posteriors for every word's label.

$$\hat{s}_i = \arg \max_{s \in \mathcal{S}} p(S_i = s | \mathbf{x}; \theta)$$

- This is sometimes called **posterior decoding**.
- Compare with **MAP decoding** (sometimes called **Viterbi decoding**):

$$\hat{\mathbf{s}} = \arg \max_{\mathbf{s} \in \mathcal{S}^n} p(\mathbf{s} | \mathbf{x}; \theta)$$

Calculate $p(x_1 \dots x_n, S_{j-1} = s', S_j = s)$ is similar to $p(x_1 \dots x_n, S_j = s)$.

Unsupervised training for an HMM

Now we are able to compute *expected counts*:

$$\underline{\text{count}}(s \rightarrow s') = E_{\theta}(s \rightarrow s' | \mathbf{x}^{(i)})$$

and

$$\underline{\text{count}}(s \rightarrow x) = E_{\theta}(s \rightarrow x | \mathbf{x}^{(i)})$$

Then we are able to learn parameters using EM!

Improving supervised HMM tagger

Treat additional information as latent variables

Profits/N soared/V at/P Boeing/N Co./N ,/, easily/ADV
topping/V forecasts/N on/P Wall/N Street/N ,/, as/P
their/POSS CEO/N Alan/N Mulally/N announced/V first/ADJ
quarter/N results/N

Bigram	92.25
Bigram+LA	94.53

Improving supervised HMM tagger

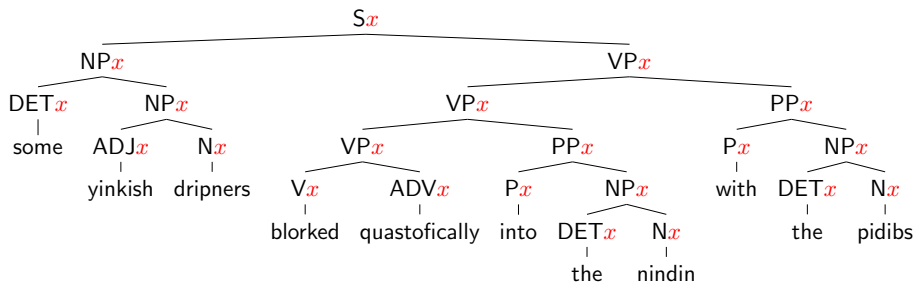
Treat additional information as latent variables

Profits/N_x soared/V_x at/P_x Boeing/N_x Co./N_x ,/,_x easily/ADV_x
topping/V_x forecasts/N_x on/P_x Wall/N_x Street/N_x ,/,_x as/P_x
their/POSS_x CEO/N_x Alan/N_x Mulally/N_x announced/V_x first/ADJ_x
quarter/N_x results/N_x

Bigram	92.25
Bigram+LA	94.53

Improving supervised PCFG parsing

Latent annotation or symbol refinement



Improvement: roughly 72.6 $\rightarrow$ 91.1.

Compound PCFG for grammar induction

Kim et al. (2019)

<https://aclanthology.org/P19-1228.pdf>

$$q(T \rightarrow w; \mathbf{z}) = \frac{\exp(\mathbf{u}_w^\top f_2([\mathbf{w}_T; \mathbf{z}]))}{\sum_{w' \in \Sigma} \exp(\mathbf{u}_{w'}^\top f_2([\mathbf{w}_T; \mathbf{z}]))}$$

$$q(A \rightarrow BC; \mathbf{z}) = \frac{\exp(\mathbf{u}_{BC}^\top [\mathbf{w}_A; \mathbf{z}])}{\sum_{B'C'} \exp(\mathbf{u}_{B'C'}^\top [\mathbf{w}_A; \mathbf{z}])}$$

Where

$$\begin{aligned} f_i(\mathbf{x}) &= g_{i,1}(g_{i,2}(W_i, \mathbf{x})) \\ g_{i,j}(\mathbf{y}) &= \text{ReLU}(V_{i,j} \text{ReLU}(U_{i,j} \mathbf{y})) + \mathbf{y} \end{aligned}$$

Readings

- Appendix A: Hidden Markov Models. *Speech and Language Processing*.
D Jurafsky and J Martin.
<https://web.stanford.edu/~jurafsky/slp3/A.pdf>